

PART 1: COMPUTATIONAL CAPABILITIES OF RECURRENT NEURAL NETWORKS

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Université Paris II

4 October 2016

INTRODUCTION

- ▶ We assume that some aspects of information processing in the brain can be approached from the perspective of computability theory.
- ▶ We consider neural network models involved in various (bio-inspired) computational paradigms.
- ▶ We analyze their computational capabilities...

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Computer Science



Biology

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Artificial Neural Networks

Machine Learning

Computational neuroscience

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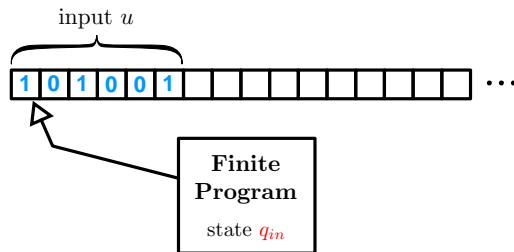
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Theoretical
Computer Science

Biology

TURING MACHINE

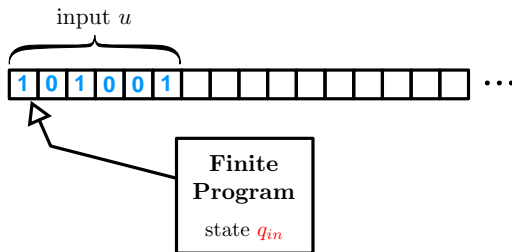
A *Turing machine* (TM) consists of an infinite tape, a read-write head, and a finite program.



- ▶ input u is *accepted* by \mathcal{M} if $\mathcal{M}(u)$ reaches the state q_{acc}
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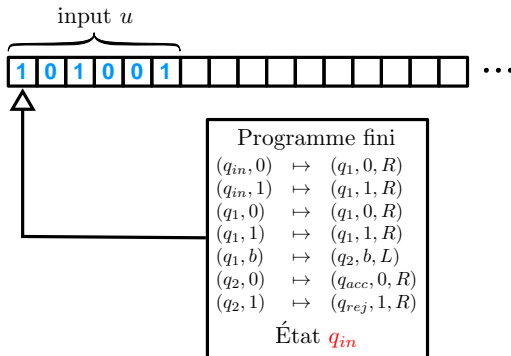
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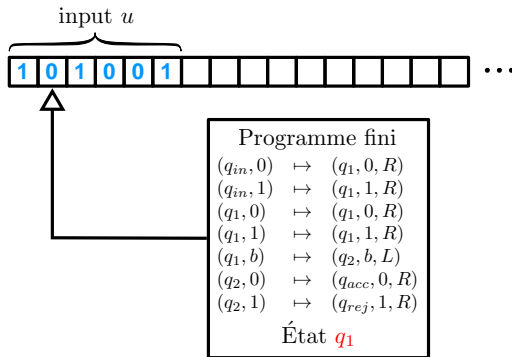


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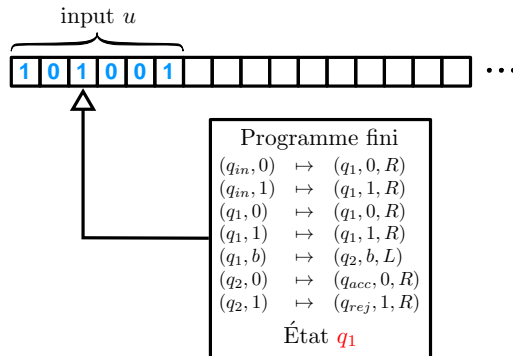


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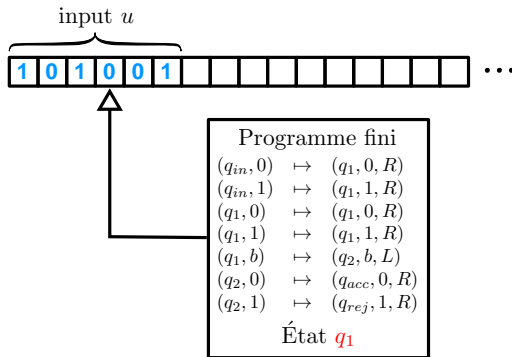


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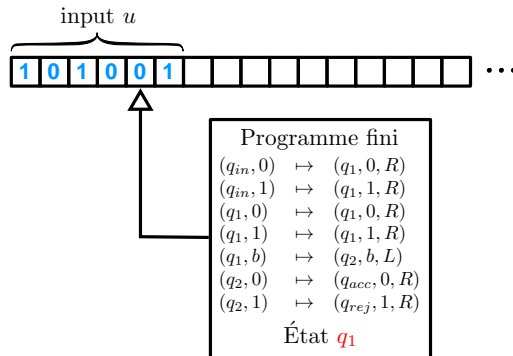


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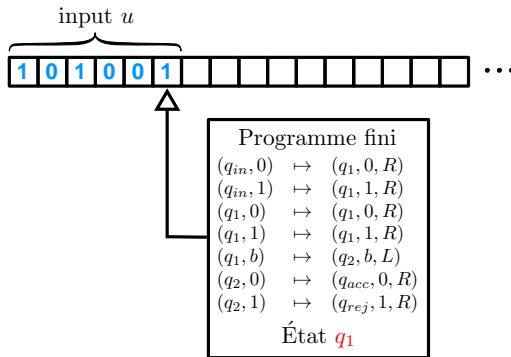


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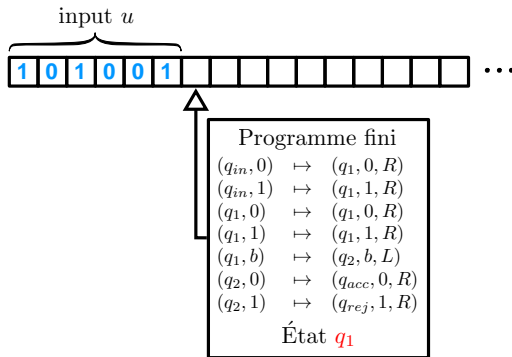


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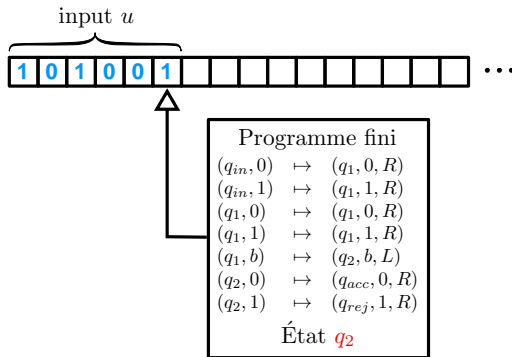


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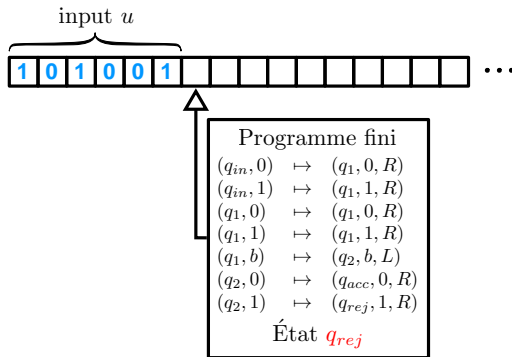


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CHURCH-TURING THESIS

A function is effectively computable if and only if it is Turing-computable.

- ▶ Informal statement setting the limits of effective computation.
- ▶ Implications in philosophy of mind, theoretical psychology, cognitive science, Artificial Intelligence, and Artificial Life.
- ▶ Sometimes under debate...

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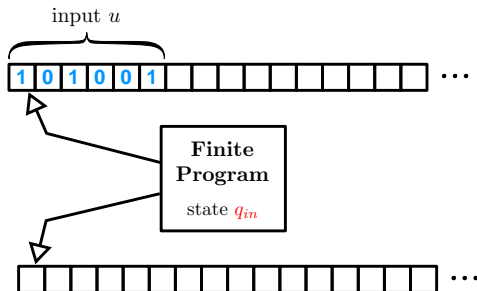
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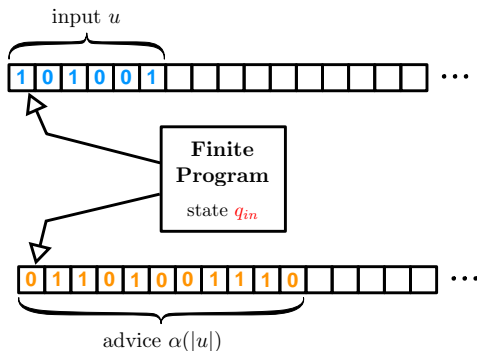
TURING MACHINE WITH ADVICE

A *Turing machine with advice* (TM/A) is a TM provided with an additional advice tape and advice function $\alpha : \mathbb{N} \longrightarrow \{0, 1\}^*$.



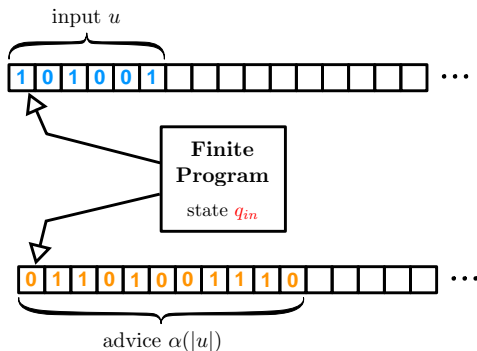
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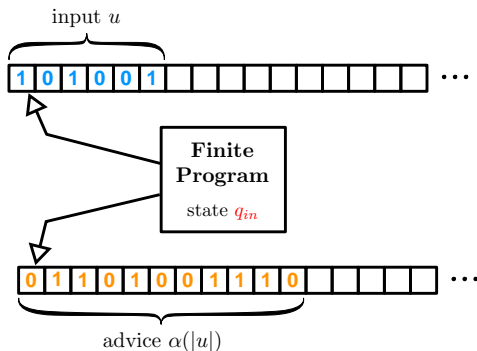
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- **P/poly** is the class of languages recognized in polynomial time by Turing machines with polynomial advices (TM/poly(A)).

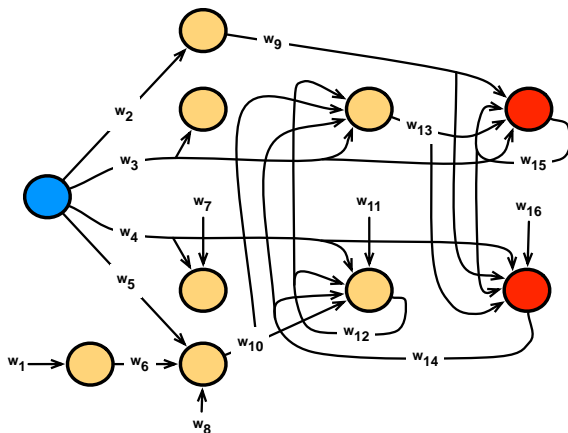
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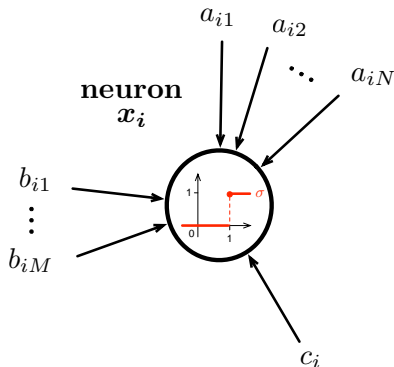


- A TM/A is strictly more powerful than a TM...
We call this *super-Turing*.

RECURRENT NEURAL NETWORK

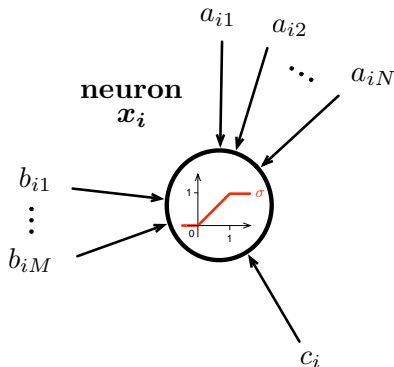


BOOLEAN RECURRENT NEURAL NETWORKS



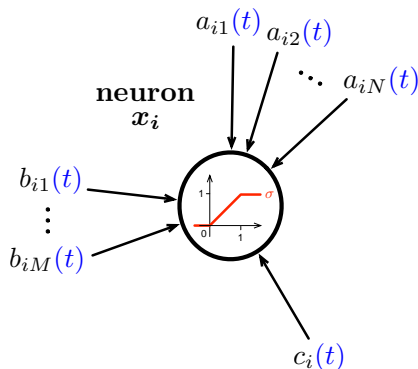
$$x_i(t+1) = \theta \left(\sum_{j=1}^N a_{ij} \cdot x_j(t) + \sum_{j=1}^M b_{ij} \cdot u_j(t) + c_i \right)$$

SIGMOIDAL RECURRENT NEURAL NETWORKS



$$x_i(t+1) = \sigma \left(\sum_{j=1}^N a_{ij} \cdot x_j(t) + \sum_{j=1}^M b_{ij} \cdot u_j(t) + c_i \right)$$

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NEURAL ACTIVITY

Video of firing neurons...

▶ [Link](#)

RECURRENT NEURAL NETWORKS

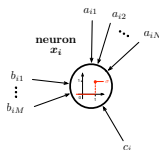
We consider eight models of RNNs:

1. Boolean rational RNNs:	$B\text{-RNN}[\mathbb{Q}]_s$
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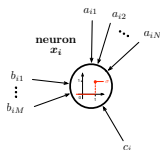


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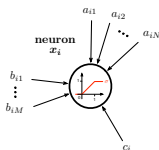


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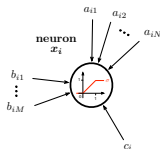


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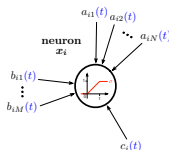


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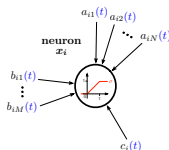


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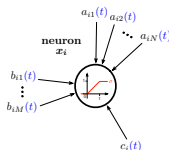


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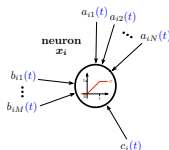


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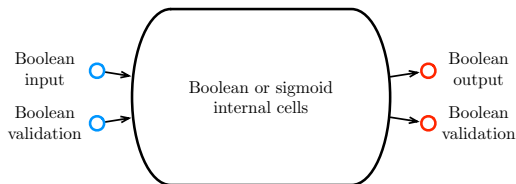
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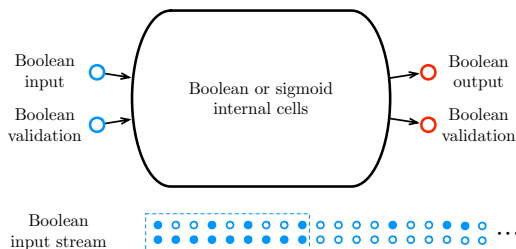


► Input stream $s \in \mathbb{B}^*$ *rejected* by \mathcal{N} iff $\mathcal{N}(s) = 0$.

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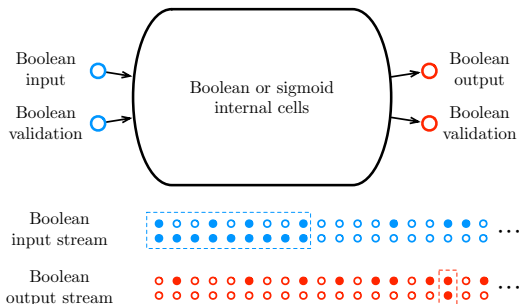
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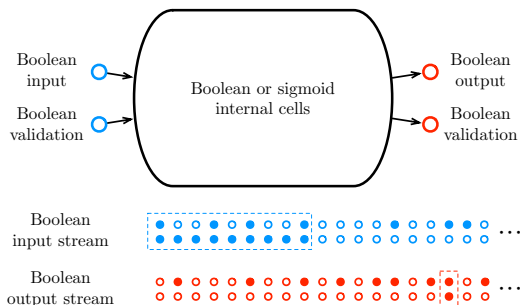
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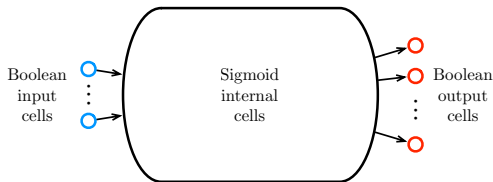
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- ▶ Input stream $s \in \mathbb{B}^*$ *accepted* by \mathcal{N} iff $\mathcal{N}(s) = 1$.

RESULTS

	BOOLEAN	STATIC	BI-VALUED	EVOLVING
\mathbb{Q}	FSA	TM	TM/poly(A)	TM/poly(A)
	REG	P	P/poly	P/poly
	KI 56, Mi 67	Si & So 95	Ca & Si 11,14	Ca & Si 11,14
\mathbb{R}	FSA	TM/poly(A)	TM/poly(A)	TM/poly(A)
	REG	P/poly	P/poly	P/poly
	KI 56, Mi 67	Si & So 94	Ca & Si 11,14	Ca & Si 11,14

DETERMINISTIC ω -RNNs

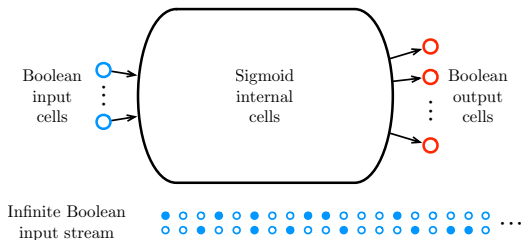
We consider RNNs with Boolean input and output cells, sigmoidal internal cells, and working on infinite input streams.



- ▶ Input stream $s \in (\mathbb{B}^M)^\omega$ *accepted* by \mathcal{N} iff $\mathcal{N}(s)$ enters a meaningful attractor.
- ▶ Input stream $s \in (\mathbb{B}^M)^\omega$ *rejected* by \mathcal{N} iff $\mathcal{N}(s)$ enters a spurious attractor.

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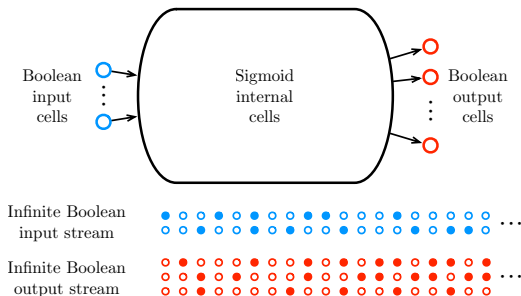
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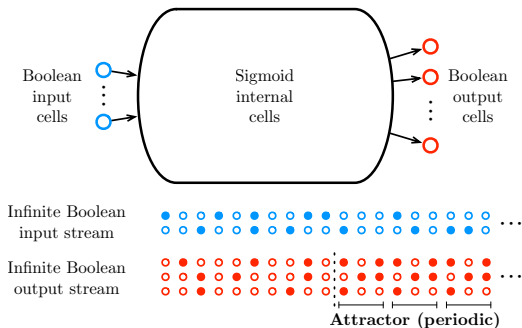
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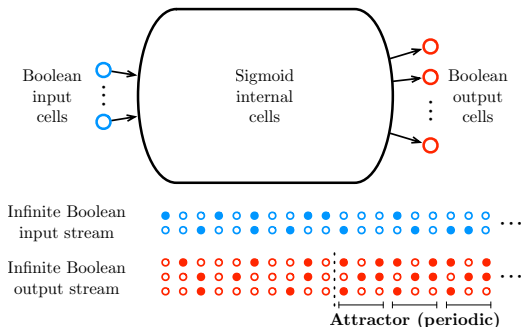
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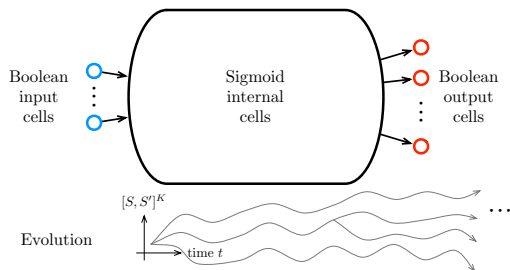
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RESULTS

DET.	STATIC	BI-VALUED EVOLVING	GENERAL EVOLVING
\mathbb{Q}	D-St-RNN[\mathbb{Q}]s $\in BC(\Pi_2^0)$ Turing (Muller)	D-Ev ₂ -RNN[\mathbb{Q}]s $= BC(\Pi_2^0)$ super-Turing	D-Ev-RNN[\mathbb{Q}]s $= BC(\Pi_2^0)$ super-Turing
\mathbb{R}	D-St-RNN[\mathbb{R}]s $= BC(\Pi_2^0)$ super-Turing	D-Ev ₂ -RNN[\mathbb{R}]s $= BC(\Pi_2^0)$ super-Turing	D-Ev-RNN[\mathbb{R}]s $= BC(\Pi_2^0)$ super-Turing

NONDETERMINISTIC ω -RNNs (TYPE II)

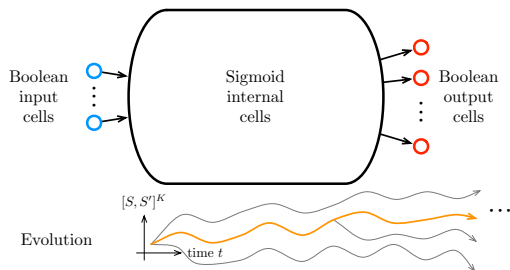
The RNNs are provided with an additional evolution set.



- Input stream $s \in (\mathbb{B}^M)^\omega$ *accepted* by \mathcal{N} iff there exists some evolution $e \in E$ s.t. $\mathcal{N}(s, e)$ enters a meaningful attractor.
- Input stream $s \in (\mathbb{B}^M)^\omega$ *rejected* by \mathcal{N} iff for all evolutions $e \in E$, $\mathcal{N}(s, e)$ does not enter a meaningful attractor.

NONDETERMINISTIC ω -RNNs (TYPE II)

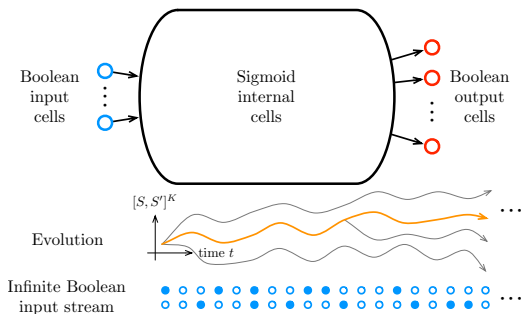
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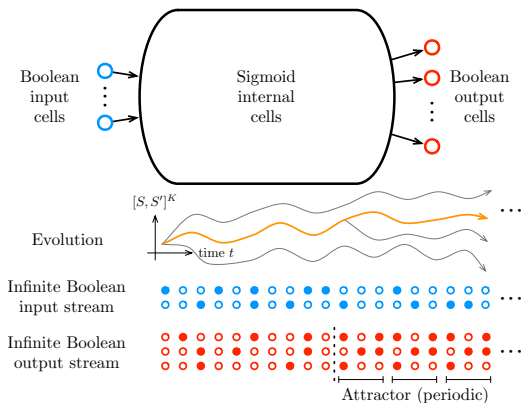
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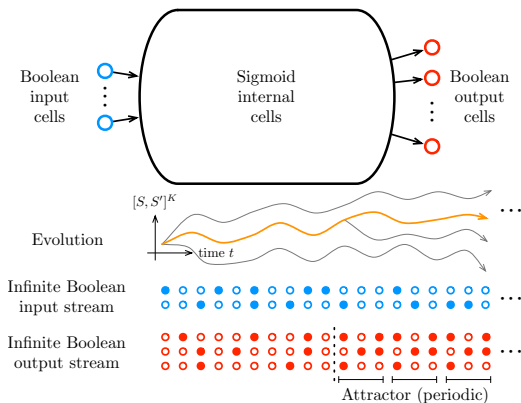
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RESULTS

NONDET.	STATIC	BI-VALUED EVOLVING	GENERAL EVOLVING
\mathbb{Q}	N-St-RNN[\mathbb{Q}]s – = Σ_1^1 (lightface) Turing (Muller)	N-Ev ₂ -RNN[\mathbb{Q}]s $\tilde{\text{N}}$ -Ev ₂ -RNN[\mathbb{Q}]s = Σ_1^1 (boldface) super-Turing	N-Ev-RNN[\mathbb{Q}]s $\tilde{\text{N}}$ -Ev-RNN[\mathbb{Q}]s = Σ_1^1 (boldface) super-Turing
\mathbb{R}	N-St-RNN[\mathbb{R}]s – = Σ_1^1 (boldface) super-Turing	N-Ev ₂ -RNN[\mathbb{R}]s $\tilde{\text{N}}$ -Ev ₂ -RNN[\mathbb{R}]s = Σ_1^1 (boldface) super-Turing	N-Ev-RNN[\mathbb{R}]s $\tilde{\text{N}}$ -Ev-RNN[\mathbb{R}]s = Σ_1^1 (boldface) super-Turing

CONCLUSIONS

- ▶ We provided a characterization of the expressive power of several models of recurrent neural networks involved in various computational paradigms.
- ▶ The power of the continuum (real synaptic weights) does add computational capabilities.
- ▶ The synaptic plasticity (evolving synaptic weights) add equivalent computational capabilities.
- ▶ Future work: super-Turing hierarchization in terms of the evolving speed of the networks.

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- ▶ Current physical theories are consistent with the possibility of hypercomputational systems (e.g., quantum, relativistic). No such systems are currently feasible or harnessable.
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PART 2: LIMIT KNOWLEDGE: A TOPOLOGICAL APPROACH TO EPISTEMIC GAME THEORY

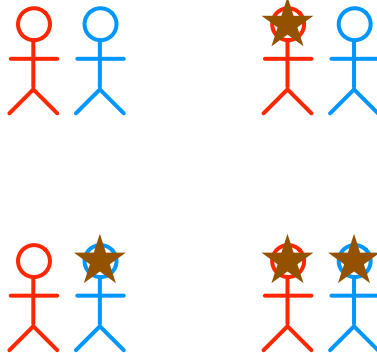
Jérémie Cabessa

Laboratoire d'Économie Mathématique (LEMMA)
Université Paris II

4 October 2016

INTRODUCTION: THE MUDDY CHILDREN PUZZLE

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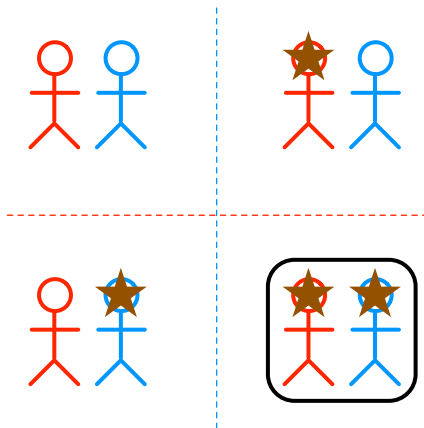
SOUTENANCE HDR



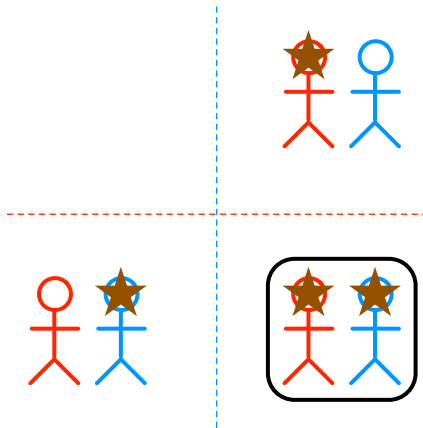
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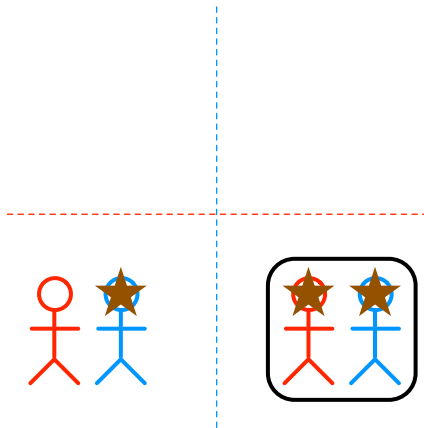
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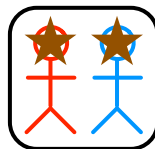
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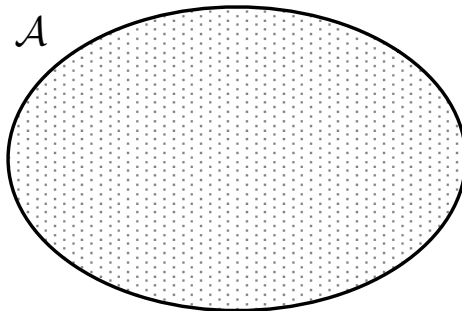
EPISTEMIC GAME THEORY

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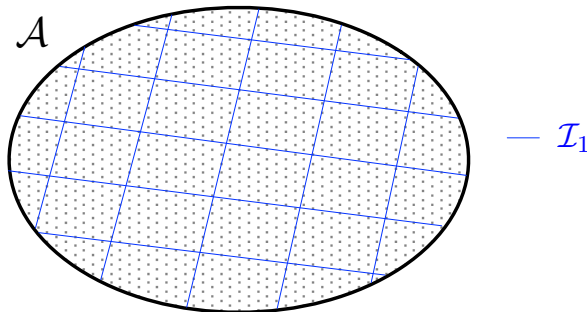
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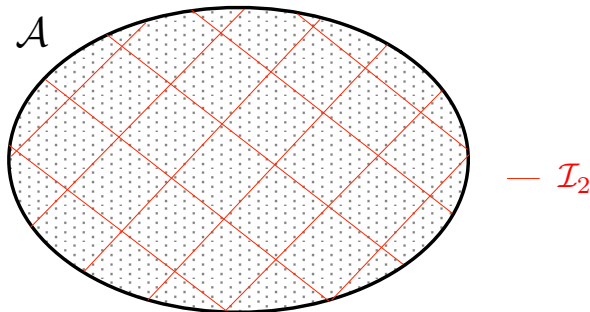
AUMANN STRUCTURES: SET-BASED APPROACH



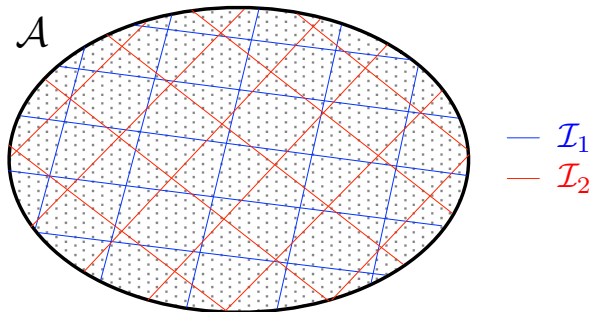
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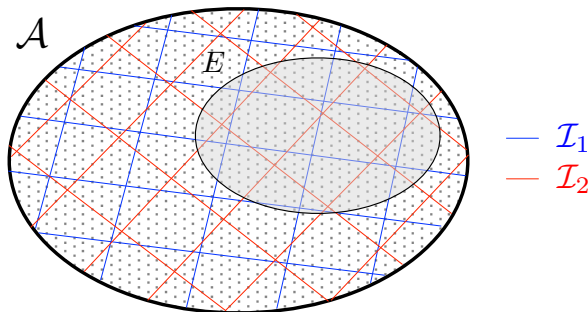
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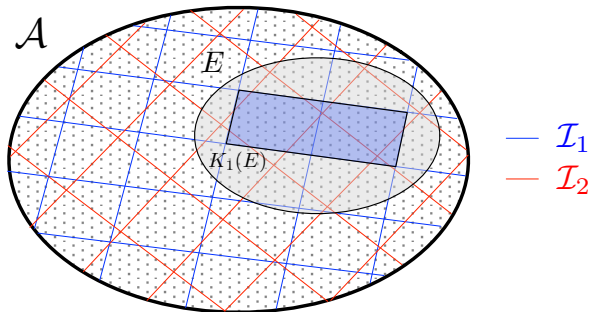
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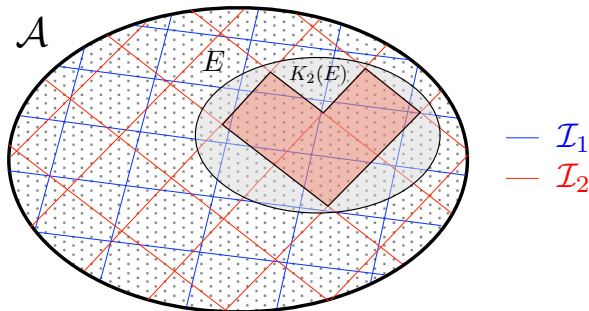
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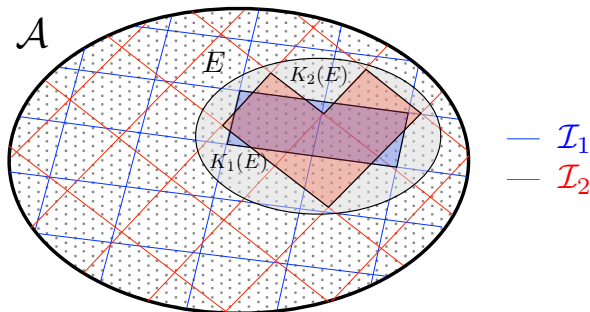
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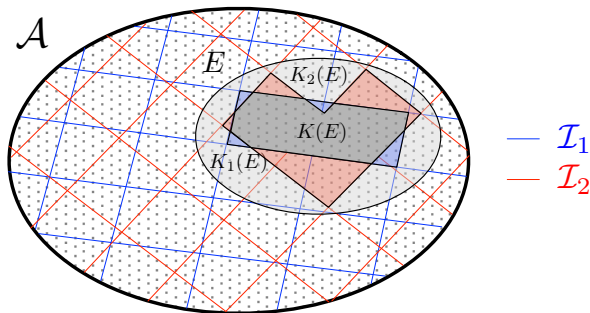
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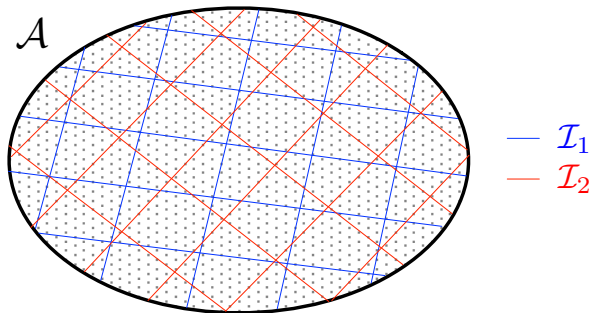
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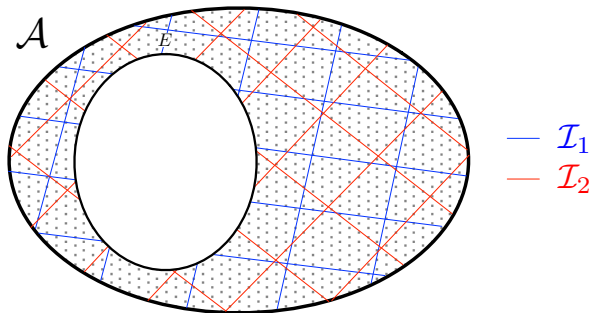
COMMON KNOWLEDGE



$$CK(E) = \bigcap_{m \geq 0} K^m(E)$$

E is *common knowledge* iff everybody knows E , and everybody knows that everybody knows E , and everybody knows that everybody knows that everybody knows E , etc.

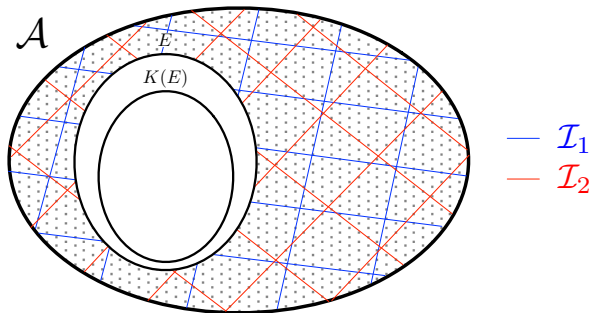
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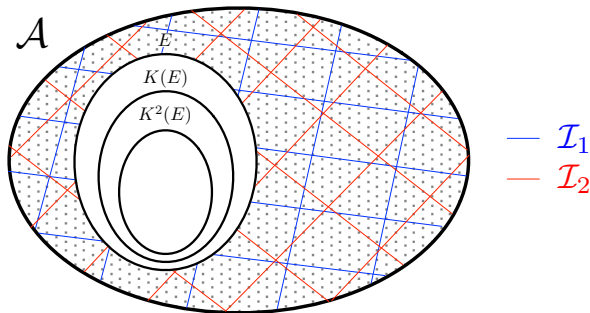
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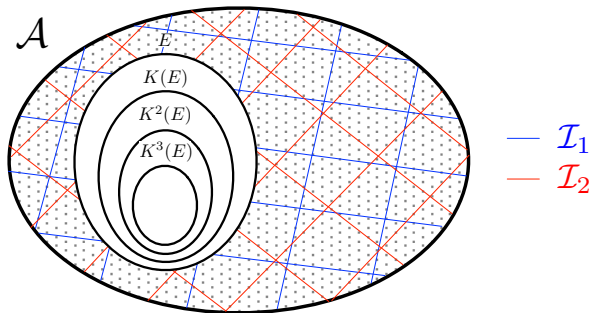
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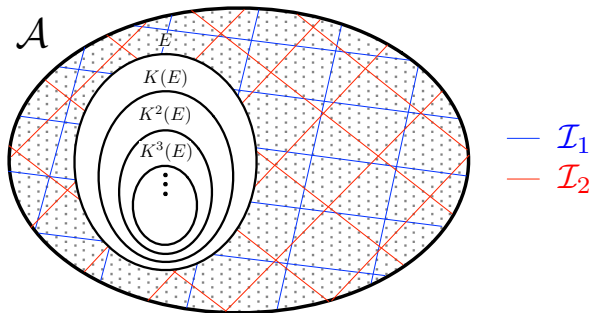
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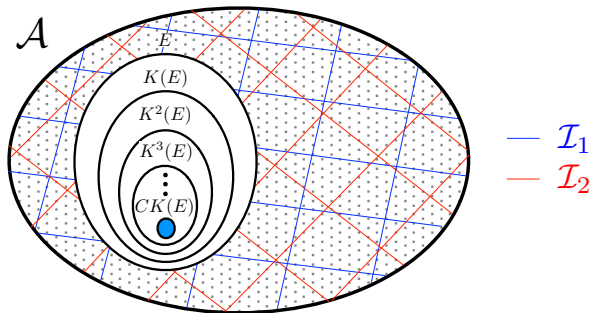
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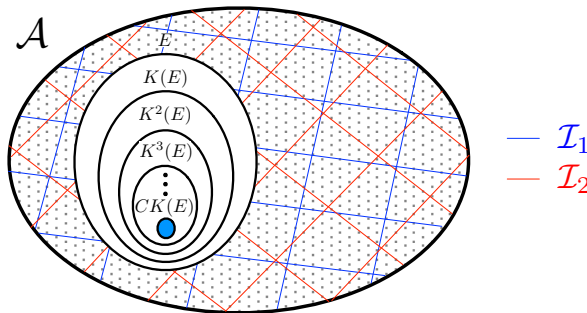
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LIMIT KNOWLEDGE

- ▶ It might be thought of that the higher-order mutual knowledge claims $K^m(E)$ become closer and closer to common knowledge $CK(E)$. But it is not the case...
- ▶ In fact, the standard set-based approach to interactive epistemology lacks a general framework providing some formal notion of closeness between events.
- ▶ An additional topological dimension introduces a perception of closeness between events.

LIMIT KNOWLEDGE

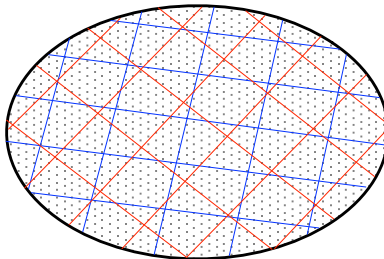
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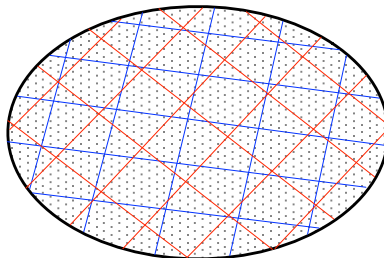
LIMIT KNOWLEDGE

$$\mathcal{A} = (\Omega, (\mathcal{I}_i)_{i \in I}, p)$$

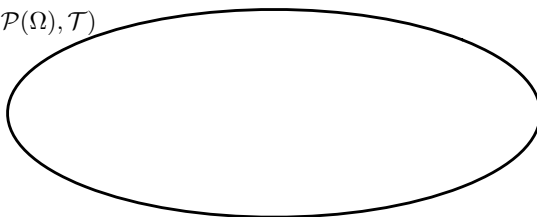


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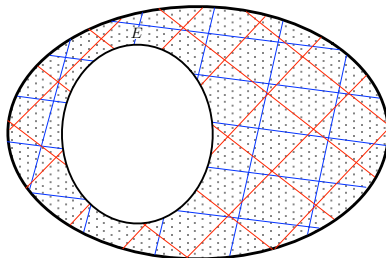


$$(\mathcal{P}(\Omega), \mathcal{T})$$

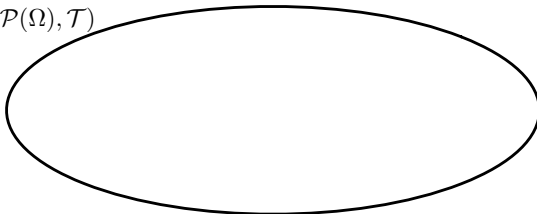


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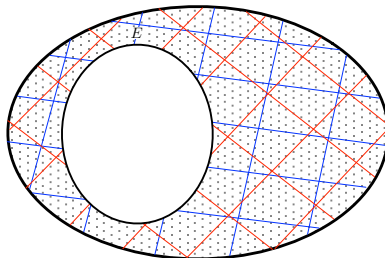


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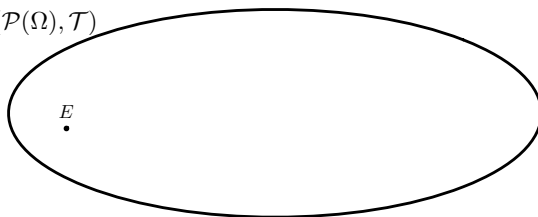


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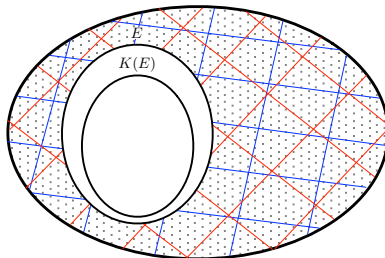


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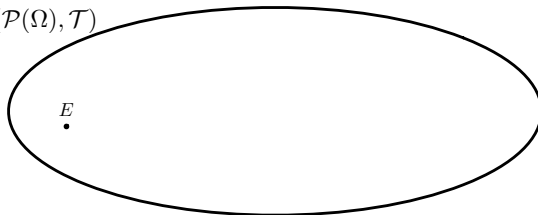


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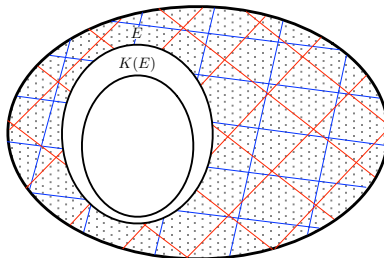


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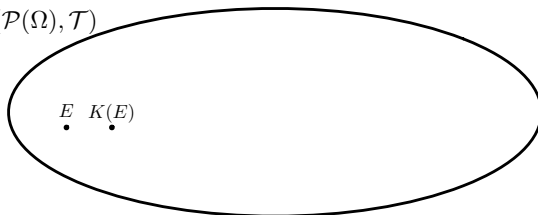


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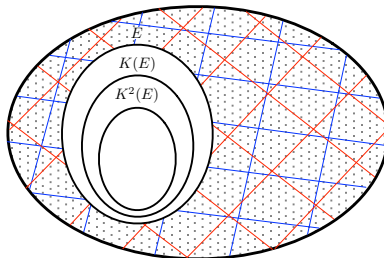


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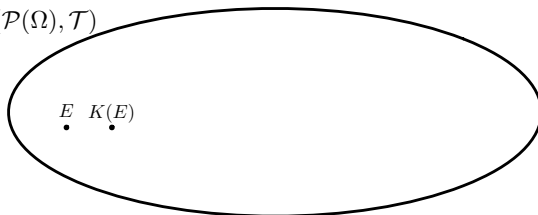


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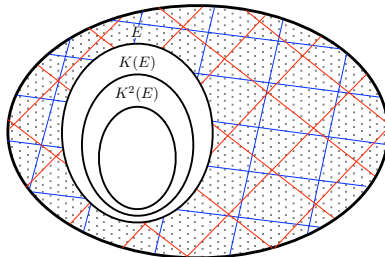


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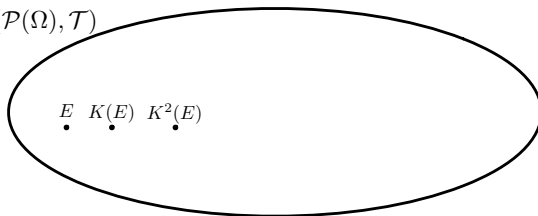


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$$\mathcal{A} = (\Omega, (\mathcal{I}_i)_{i \in I}, p)$$

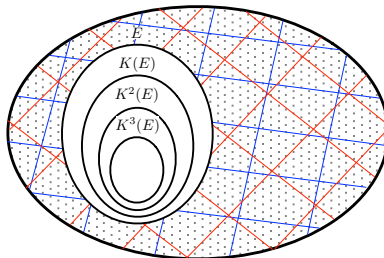


$$(\mathcal{P}(\Omega), \mathcal{T})$$

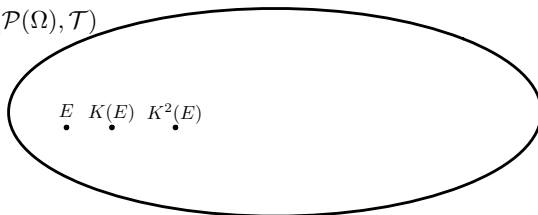


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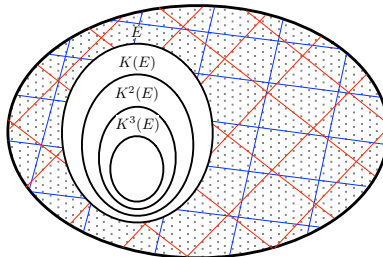


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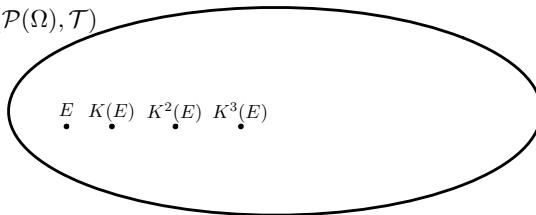


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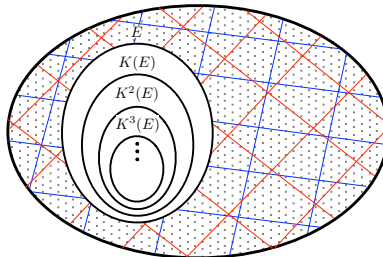


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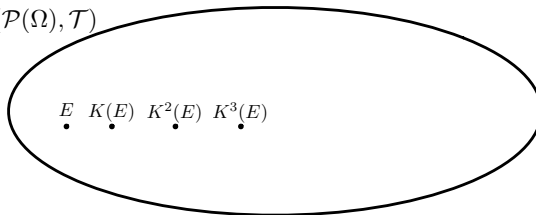


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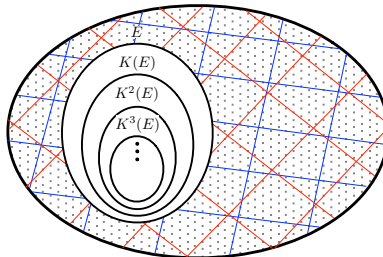


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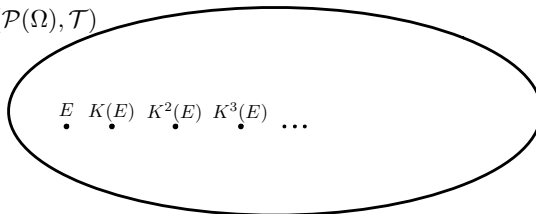


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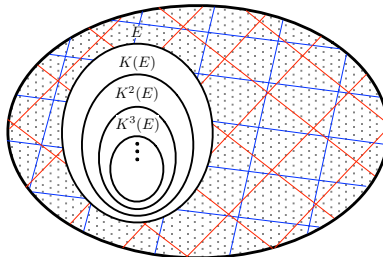


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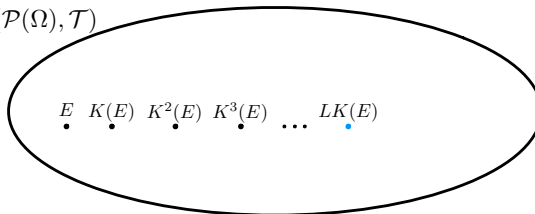


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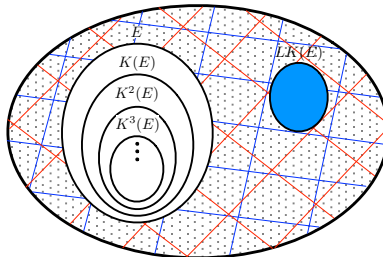


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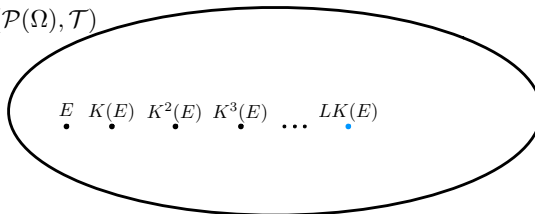


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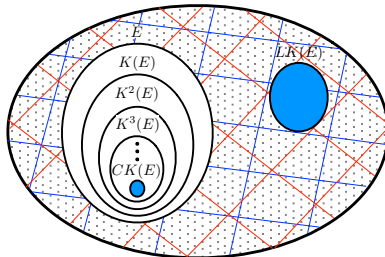


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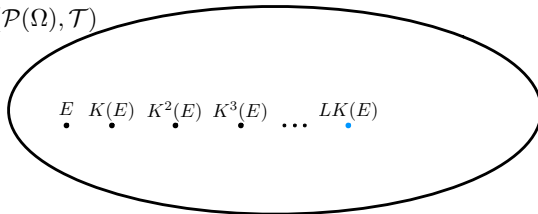


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LIMIT KNOWLEDGE

We now consider the following epistemic-topological operator *limit knowledge*.

DEFINITION 1 (LIMIT KNOWLEDGE)

Let \mathcal{A} be a topological Aumann structure, and E be some event. If the (topological) limit point of the sequence of iterated mutual knowledge claims $(K^m(E))_{m>0}$ is unique, then

$$LK(E) := \lim_{m \rightarrow \infty} K^m(E)$$

is the event that E is *limit knowledge* among the set I of agents.

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LIMIT KNOWLEDGE

Limit knowledge can be understood as the event which is approached by the sequence of iterated mutual knowledge, according to some notion of closeness between events (provided by a topology on the event space).

LIMIT KNOWLEDGE, GAMES, AND AUMANN'S AGREEMENT THEOREM

- ▶ *Limit knowledge* can provide alternative epistemic-topological characterizations of solution concepts in games.
- ▶ *Limit knowledge of rationality* can even potentially characterize any possible event and solution concept.
- ▶ Aumann's Agreement Theorem (1976): "Agents cannot agree to disagree". Limiting result: No-Trade Theorem: *agents and events agree*; Study of weakened or modified epistemic assumptions: *topologies and information structures*; Research: *epistemic logics*; *epistemic games*; *epistemic decision theory*; *epistemic decision models*; *epistemic decision problems*; *epistemic decision solutions*.
- ▶ We proved that "agents can limit-agree to disagree" . . .

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CONCLUSION

- ▶ Limit knowledge is a new epistemic-topological operator capable of capturing reasoning patterns of agents based on closeness of events.
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