

# A Classification of Neural Networks

Jérémie Cabessa

University Joseph Fourier – Grenoble 1

10 May 2009

# Outline

## 1 Introduction

## 2 Neural nets and automata

## 3 A classification of neural nets

## 4 Conclusion

# Outline

## 1 Introduction

## 2 Neural nets and automata

## 3 A classification of neural nets

## 4 Conclusion

# Outline

- 1 Introduction**
- 2 Neural nets and automata**
- 3 A classification of neural nets**
- 4 Conclusion

# Outline

- 1 Introduction
- 2 Neural nets and automata
- 3 A classification of neural nets
- 4 Conclusion



# Introduction

In 1967, Minsky proved the equivalence between McCulloch and Pitts's neural nets and finite state machines.

We extend this result for infinite word reading machines, and provide a refined classification of simple neural nets.



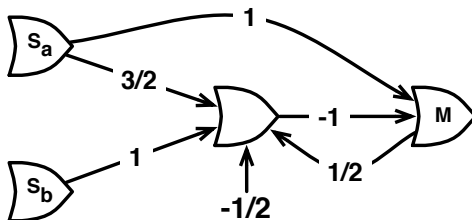
# Introduction

In 1967, Minsky proved the equivalence between McCulloch and Pitts's neural nets and finite state machines.

We extend this result for infinite word reading machines, and provide a refined classification of simple neural nets.

# Neural nets and automata

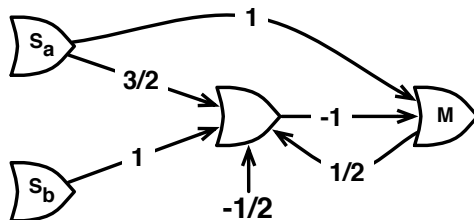
## McCulloch & Pitts' neural net





# Neural nets and automata

## McCulloch & Pitts' neural net



*stimulus* abbabbabbabb.....

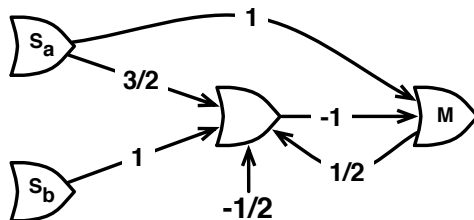
accepted

*stimulus* bbbbbbbbbbbb.....

rejected

# Neural nets and automata

## McCulloch & Pitts' neural net



*stimulus* abbabbabbabb.....

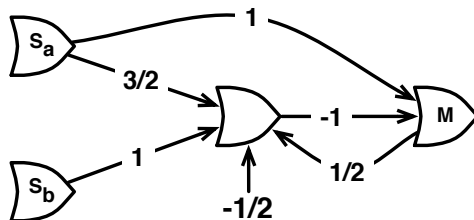
**accepted**

*stimulus* bbbbbbbbbbbb.....

**rejected**

# Neural nets and automata

## McCulloch & Pitts' neural net



stimulus *abbabbabbabb*.....

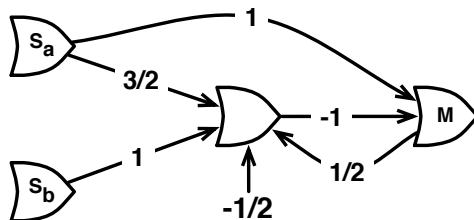
**accepted**

stimulus *bbbbbbbbbbbb*.....

**rejected**

# Neural nets and automata

## McCulloch & Pitts' neural net

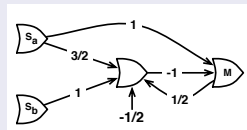


The set of stimuli accepted by this net is the *language recognized by this net*.

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

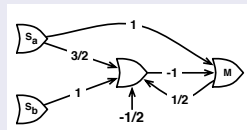
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

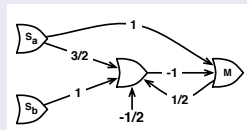
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

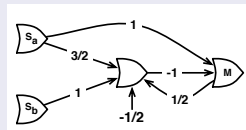
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

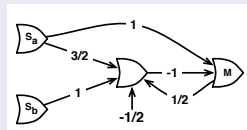
- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .



## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

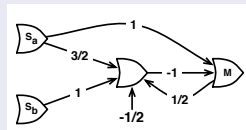
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

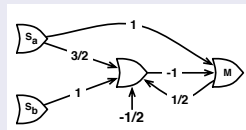
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

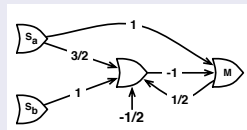
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$\omega$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.



The dynamic of cell  $i$  is given by

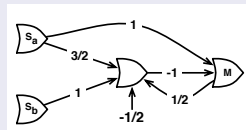
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$w$ -language recognized by  $\mathcal{N}$* .

## Definition

A *MP neural net* is a tuple  $\mathcal{N} = (C, S, M, w, b)$ , where

- $C$  is a finite set of cells,
- $S \subseteq C$  is a set of sensory cells,
- $M \subseteq C$  is a set of motor cells,
- $w : C \times C \rightarrow \mathbb{Q}$  gives the weights of the connections,
- $b : C \rightarrow \mathbb{Q}$  gives the background activity.

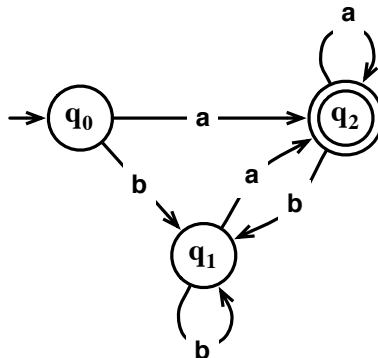


The dynamic of cell  $i$  is given by

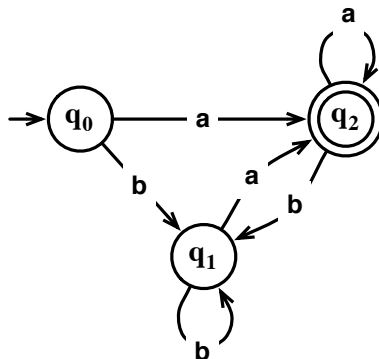
$$x_i(t+1) = \sigma \left( \sum_{j \in C} w(j, i) \cdot x_j(t) + b(i) \right), \text{ where } \sigma(x) = \begin{cases} 0 & \text{if } x < 1, \\ 1 & \text{if } x \geq 1. \end{cases}$$

- An infinite stimulus  $w$  is *accepted* by  $\mathcal{N}$  iff it evokes infinitely many motor responses.
- The set of infinite stimuli accepted by  $\mathcal{N}$  is called the  *$\omega$ -language recognized by  $\mathcal{N}$* .

## Büchi automaton



## Büchi automaton



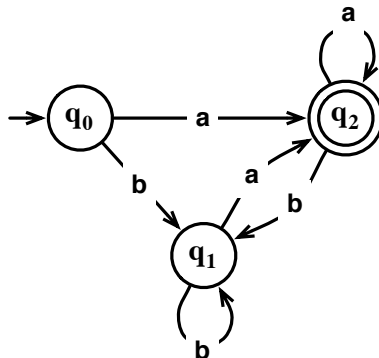
*input* *abababab* .....

*accepted*

*input* *baabbbbbb* .....

*rejected*

## Büchi automaton



*input* *abababab* .....

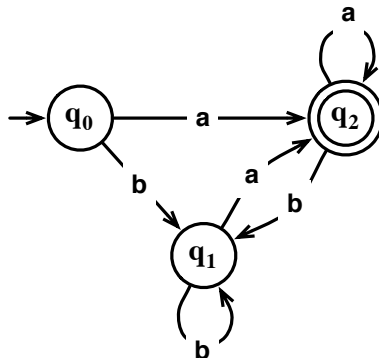
**accepted**

*input* *baabbbbbb* .....

**rejected**



## Büchi automaton



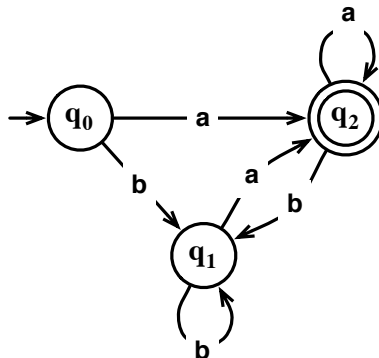
*input* *abababab* .....

**accepted**

*input* *baabbbbb* .....

**rejected**

## Büchi automaton

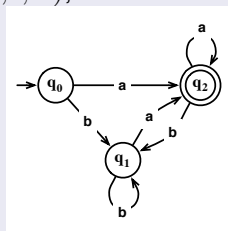


The set of words accepted by this automaton is the *language recognized by this automaton*.

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.

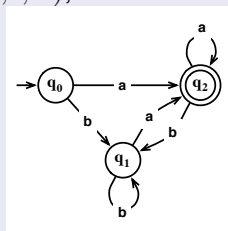


- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.

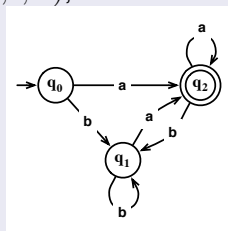


- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.

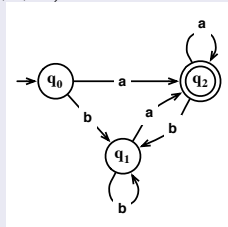


- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.

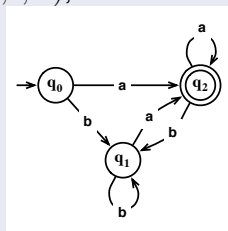


- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.

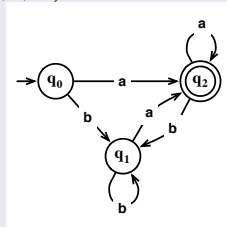


- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.



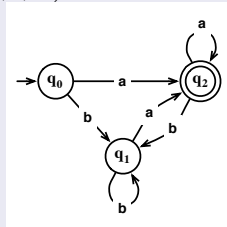
- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $Inf(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .



## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.

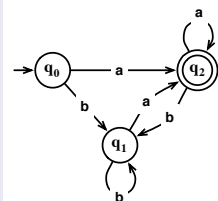


- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Definition

A *det. Büchi automaton* is a tuple  $\mathcal{A} = (Q, A, \delta, i, F)$ , where

- $Q$  is a finite set of states,
- $A$  is an alphabet,
- $\delta : Q \times A \longrightarrow Q$  is the transition function,
- $i \in Q$  is the initial state,
- $F \subseteq Q$  is the set of finite states.



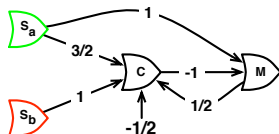
- An infinite input  $w$  over  $A$  is *accepted* by  $\mathcal{A}$  iff  $\text{Inf}(w) \cap F \neq \emptyset$ .
- The set of infinite words accepted by  $\mathcal{A}$  is called the  *$\omega$ -language recognized by  $\mathcal{A}$* .

## Theorem

*Let  $L$  be an  $\omega$ -language. Then the following are equivalent:*

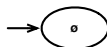
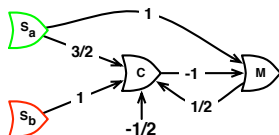
- 1**  *$L$  is recognizable by some MP neural net;*
- 2**  *$L$  is recognizable by some det. Büchi automata;*

*Proof:* (1)  $\Rightarrow$  (2): From MP neural nets to det. Büchi automata...



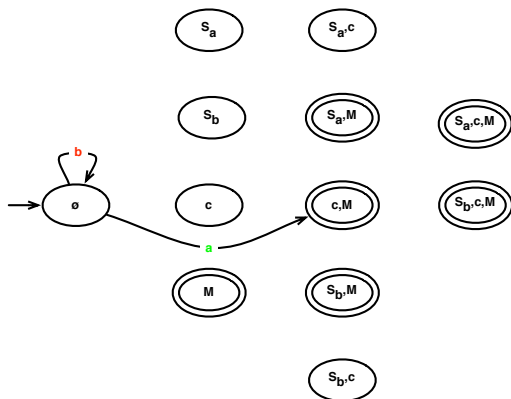
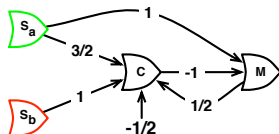
By construction,  $L(\mathcal{N}) = L(\mathcal{A})$ .

*Proof:* (1)  $\Rightarrow$  (2): From MP neural nets to det. Büchi automata...



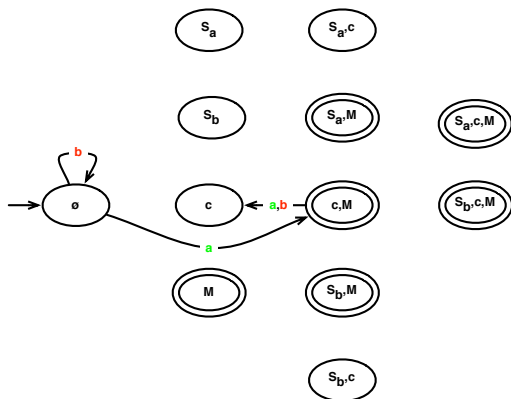
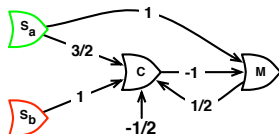
By construction,  $L(\mathcal{N}) = L(\mathcal{A})$ .

*Proof:* (1)  $\Rightarrow$  (2): From MP neural nets to det. Büchi automata...



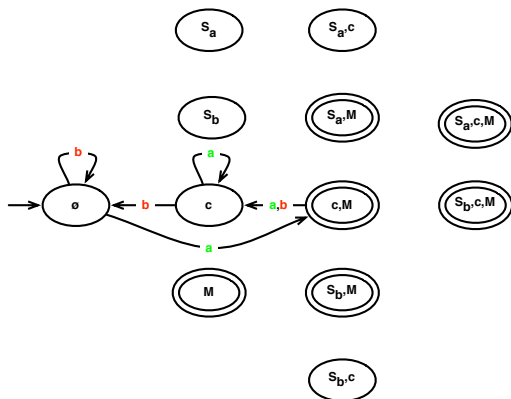
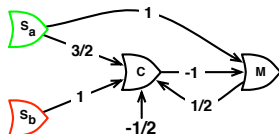
By construction,  $L(\mathcal{N}) = L(\mathcal{A})$ .

*Proof:* (1)  $\Rightarrow$  (2): From MP neural nets to det. Büchi automata...



By construction,  $L(\mathcal{N}) = L(\mathcal{A})$ .

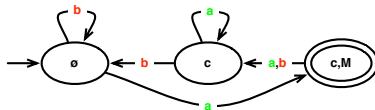
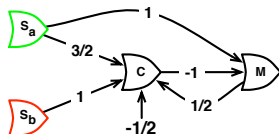
*Proof:* (1)  $\Rightarrow$  (2): From MP neural nets to det. Büchi automata...



By construction,  $L(\mathcal{N}) = L(\mathcal{A})$ .

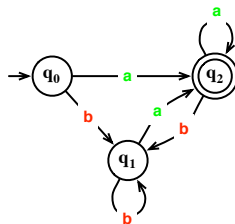


*Proof:* (1)  $\Rightarrow$  (2): From MP neural nets to det. Büchi automata...



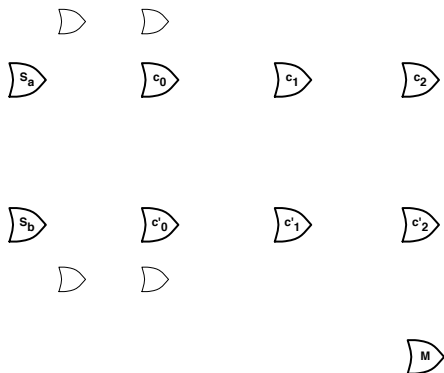
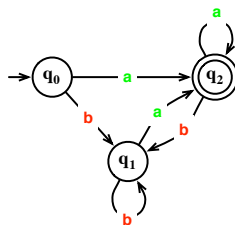
By construction,  $L(\mathcal{N}) = L(\mathcal{A})$ .

(2)  $\Rightarrow$  (1): From det. Büchi automata to MP neural nets...



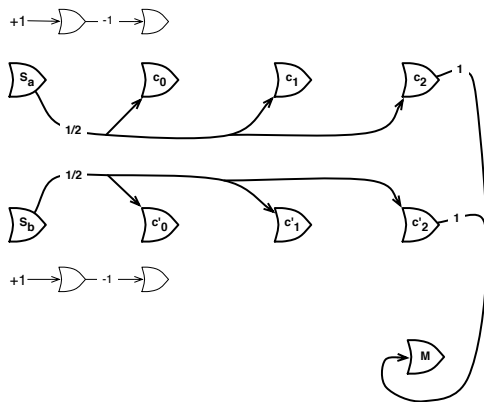
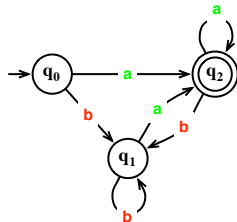
By construction,  $L(\mathcal{A}) = L(\mathcal{N})$ .

(2)  $\Rightarrow$  (1): From det. Büchi automata to MP neural nets...

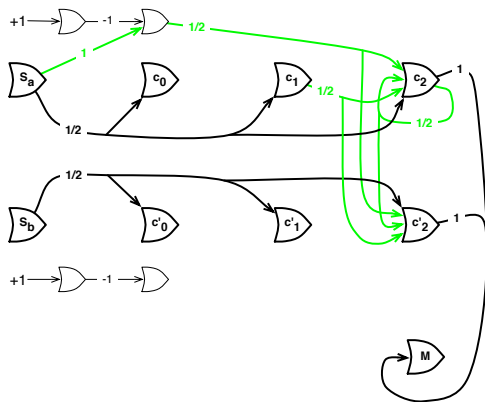
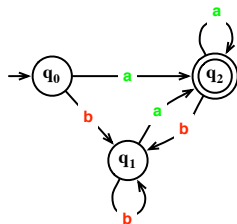


By construction,  $L(\mathcal{A}) = L(\mathcal{N})$ .

(2)  $\Rightarrow$  (1): From det. Büchi automata to MP neural nets...

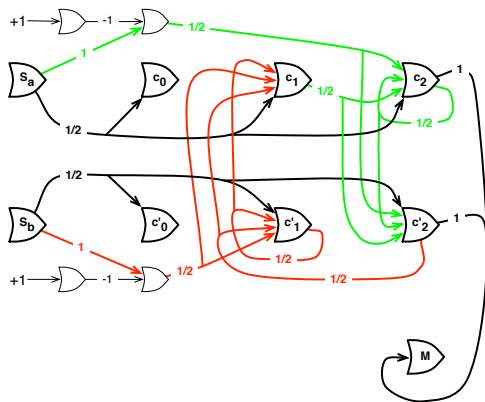
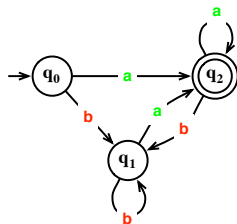


(2)  $\Rightarrow$  (1): From det. Büchi automata to MP neural nets...



By construction,  $L(\mathcal{A}) = L(\mathcal{N})$ .

(2)  $\Rightarrow$  (1): From det. Büchi automata to MP neural nets...



By construction,  $L(\mathcal{A}) = L(\mathcal{N})$ .



# A classification of neural nets

Let  $A$  and  $B$  be two  $\omega$ -languages:

$A \leq_W B$     iff    there exists  $f$  continuous s.t.  $A = f^{-1}(B)$

iff    there exists  $f$  continuous s.t.  $x \in A \Leftrightarrow f(x) \in B$

Then as usual

$A <_W B$     iff     $A \leq_W B$  and  $B \not\leq_W A$

$A \equiv_W B$     iff     $A \leq_W B$  and  $B \leq_W A$

# A classification of neural nets

Let  $A$  and  $B$  be two  $\omega$ -languages:

$$\begin{aligned}
 A \leq_W B \quad \text{iff} \quad & \text{there exists } f \text{ continuous s.t. } A = f^{-1}(B) \\
 \text{iff} \quad & \text{there exists } f \text{ continuous s.t. } x \in A \Leftrightarrow f(x) \in B
 \end{aligned}$$

Then as usual

$$A <_W B \quad \text{iff} \quad A \leq_W B \text{ and } B \not\leq_W A$$

$$A \equiv_W B \quad \text{iff} \quad A \leq_W B \text{ and } B \leq_W A$$



# A classification of neural nets

Let  $A$  and  $B$  be two  $\omega$ -languages:

$$\begin{aligned} A \leq_W B \quad \text{iff} \quad & \text{there exists } f \text{ continuous s.t. } A = f^{-1}(B) \\ \text{iff} \quad & \text{there exists } f \text{ continuous s.t. } x \in A \Leftrightarrow f(x) \in B \end{aligned}$$

Then as usual

$$\begin{aligned} A <_W B \quad \text{iff} \quad & A \leq_W B \text{ and } B \not\leq_W A \\ A \equiv_W B \quad \text{iff} \quad & A \leq_W B \text{ and } B \leq_W A \end{aligned}$$

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{\text{def}} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{def} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{def} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

**Assume that for any element  $x$ ,  
you know whether  $x \in B$  or not**

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{def} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

Does a given  $a \in A$ ?

Assume that for any element  $x$ ,  
you know whether  $x \in B$  or not

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{def} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

Does a given  $a \in A$  ?

Assume that for any element  $x$ ,  
you know whether  $x \in B$  or not

$$a \longmapsto f \longrightarrow f(a)$$

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{\text{def}} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

Does a given  $a \in A$  ?

Assume that for any element  $x$ ,  
you know whether  $x \in B$  or not

$$a \longmapsto f \longrightarrow f(a)$$

If  $f(a) \in B$ , then  $a \in A$

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{\text{def}} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

Does a given  $a \in A$  ?

Assume that for any element  $x$ ,  
you know whether  $x \in B$  or not

$$a \longmapsto f \longrightarrow f(a)$$

If  $f(a) \in B$ , then  $a \in A$

If  $f(a) \notin B$ , then  $a \notin A$

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .



$A \leq_W B$  means intuitively that  $A$  is “less complicated” than  $B$ .  
Indeed we have ...

$$A \leq_W B \quad \text{iff}_{\text{def}} \quad x \in A \Leftrightarrow f(x) \in B \quad \text{for some } f \text{ continuous}$$

Does a given  $a \in A$  ?

Assume that for any element  $x$ ,  
you know whether  $x \in B$  or not

$$a \longmapsto f \longrightarrow f(a)$$

If  $f(a) \in B$ , then  $a \in A$

If  $f(a) \notin B$ , then  $a \notin A$

In other terms, the belonging problem in  $A$  reduces via  $f$  to the belonging problem in  $B$ .

## Definition

- The collection of  $\omega$ -languages recognized by Det-Büchi automata ordered by  $\leq_W$  is called the *Det. Büchi hierarchy*.
- The collection of  $\omega$ -languages recognized by MP-neural nets ordered by  $\leq_W$  is called the *MP-neural hierarchy*.

By the previous equivalence theorem, the Det-Büchi and the MP-neural hierarchies are equal.

## Definition

- The collection of  $\omega$ -languages recognized by Det-Büchi automata ordered by  $\leq_W$  is called the *Det. Büchi hierarchy*.
- The collection of  $\omega$ -languages recognized by MP-neural nets ordered by  $\leq_W$  is called the *MP-neural hierarchy*.

By the previous equivalence theorem, the Det-Büchi and the MP-neural hierarchies are equal.

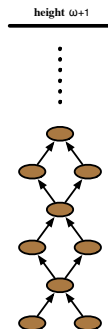
## Definition

- The collection of  $\omega$ -languages recognized by Det-Büchi automata ordered by  $\leq_W$  is called the *Det. Büchi hierarchy*.
- The collection of  $\omega$ -languages recognized by MP-neural nets ordered by  $\leq_W$  is called the *MP-neural hierarchy*.

By the previous equivalence theorem, the Det-Büchi and the MP-neural hierarchies are equal.

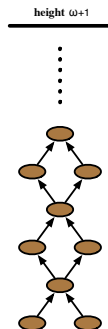
## Theorem

- *The Det-Büchi hierarchy is well-founded, has width 2 and height  $\omega + 1$ .*
- *The MP-neural hierarchy is well-founded, has width 2 and height  $\omega + 1$ .*



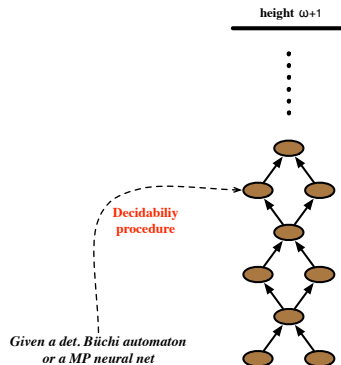
## Theorem

- *The Det-Büchi hierarchy is well-founded, has width 2 and height  $\omega + 1$ .*
- *The MP-neural hierarchy is well-founded, has width 2 and height  $\omega + 1$ .*



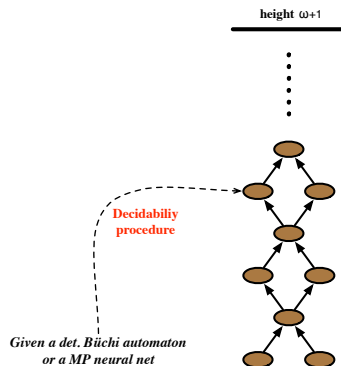
## Theorem

- *The Det-Büchi hierarchy is decidable.*
- *The MP-Neural hierarchy is decidable.*



## Theorem

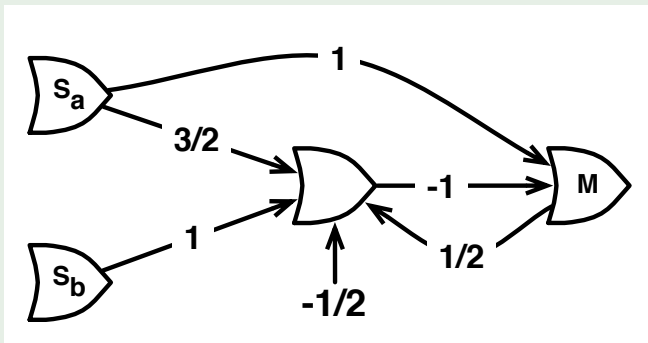
- *The Det-Büchi hierarchy is decidable.*
- *The MP-Neural hierarchy is decidable.*





## Example

Consider the following MP neural net  $\mathcal{N}$ .



Then the degree of  $L(\mathcal{N})$  in the MP-neural hierarchy is  $\omega$ .

## Significant extension of this work:

we are also able to establish another equivalence between some kind of McCulloch and Pitts' neural nets and Muller automata; this induces another decidable hierarchy of networks of height  $\omega^\omega$ .

Significant extension of this work:

we are also able to establish another equivalence between some kind of McCulloch and Pitts' neural nets and Muller automata; this induces another decidable hierarchy of networks of height  $\omega^\omega$ .

Significant extension of this work:

we are also able to establish another equivalence between some kind of McCulloch and Pitts' neural nets and Muller automata; this induces another decidable hierarchy of networks of height  $\omega^\omega$ .

# Conclusion

- We presented a decidable transfinite classification of simple neural nets based on their computational capability.
- The height of a network in this hierarchy is the new index of complexity that we propose.
- Future work: investigate the computational capabilities of more biologically plausible neural nets.

# Conclusion

- We presented a decidable transfinite classification of simple neural nets based on their computational capability.
- The height of a network in this hierarchy is the new index of complexity that we propose.
- Future work: investigate the computational capabilities of more biologically plausible neural nets.

# Conclusion

- We presented a decidable transfinite classification of simple neural nets based on their computational capability.
- The height of a network in this hierarchy is the new index of complexity that we propose.
- Future work: investigate the computational capabilities of more biologically plausible neural nets.