

EMULATION OF FINITE STATE AUTOMATA WITH RECURRENT NEURAL NETWORKS COMPOSED OF SYNFIRED RINGS

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INTRODUCTION

	BOOLEAN	STATIC	BI-VALUED EVOLVING	EVOLVING
\mathbb{Q}	FSA	TM	TM/poly(A)	TM/poly(A)
	REG	P	P/poly	P/poly
	KI 56, Mi 67	Si & So 95	Ca & Si 11,14	Ca & Si 11,14
\mathbb{R}	FSA	TM/poly(A)	TM/poly(A)	TM/poly(A)
	REG	P/poly	P/poly	P/poly
	KI 56, Mi 67	Si & So 94	Ca & Si 11,14	Ca & Si 11,14

TM: Turing complete

TM/poly(A): super-Turing

Here, we revisit the equivalence between Boolean RNNs and finite state automata from a more biological perspective.

INTRODUCTION

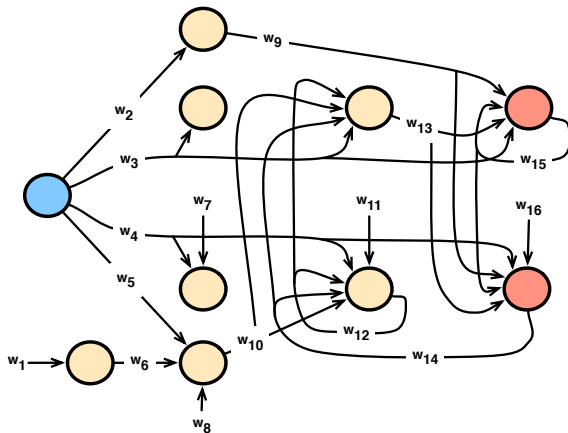
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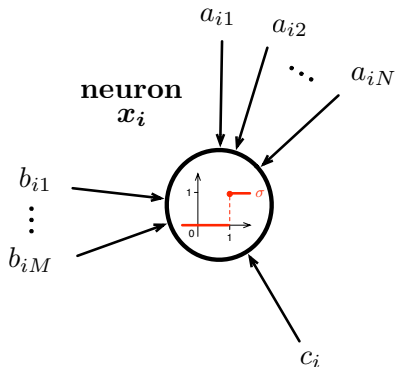
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RECURRENT NEURAL NETWORK



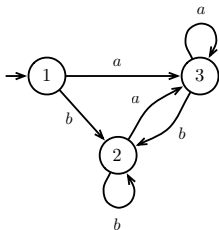
BOOLEAN RECURRENT NEURAL NETWORK



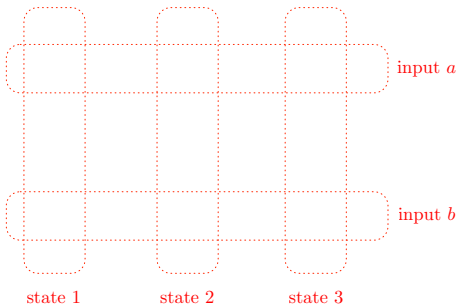
$$x_i(t+1) = \theta \left(\sum_{j=1}^N a_{ij} \cdot x_j(t) + \sum_{j=1}^M b_{ij} \cdot u_j(t) + c_i \right)$$

FROM AUTOMATA TO BOOLEAN NEURAL NETWORKS

Automaton

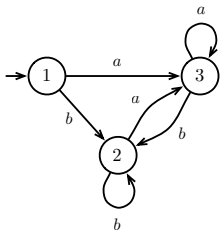


Boolean Neural Network

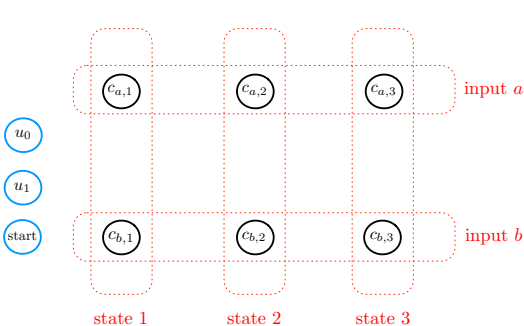


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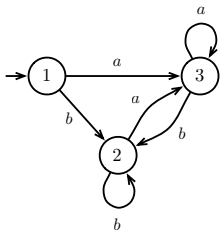


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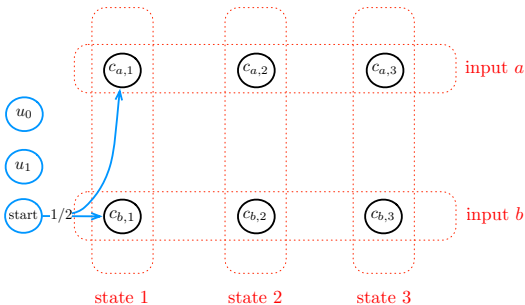


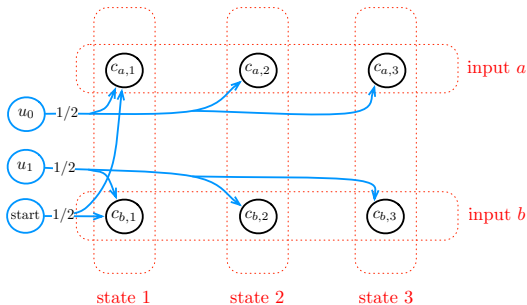
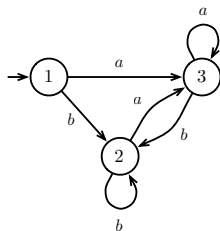
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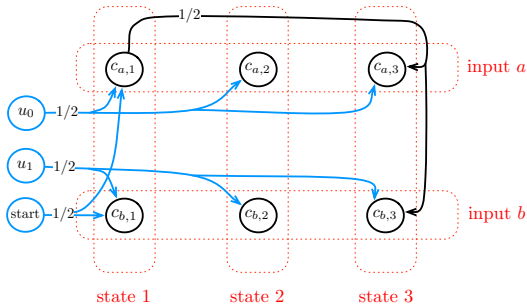
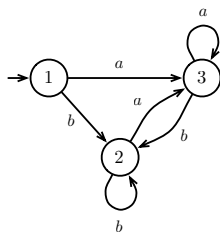
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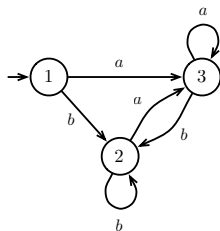




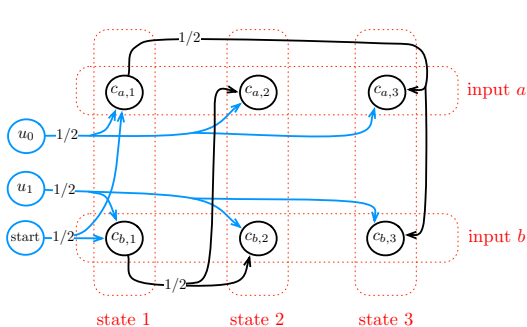


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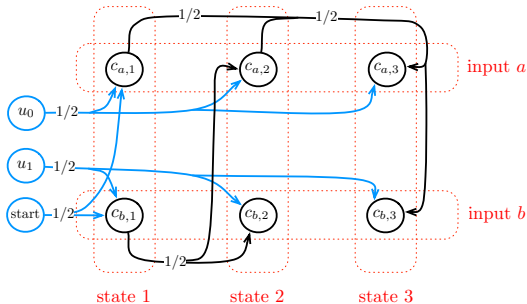
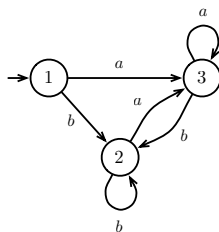
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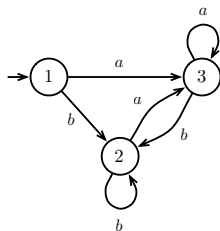
EMULATION OF FINITE STATE AUTOMATA WITH RNNs



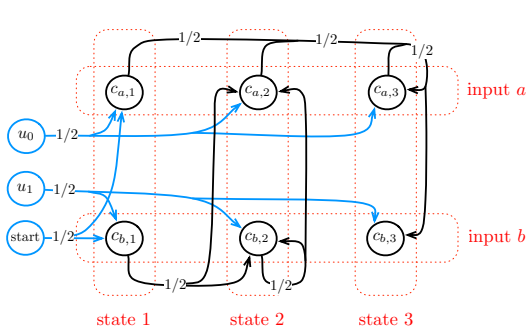
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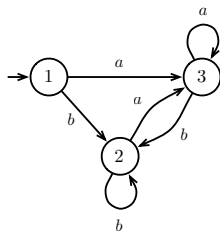


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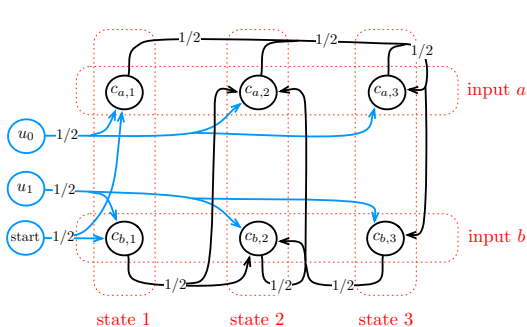


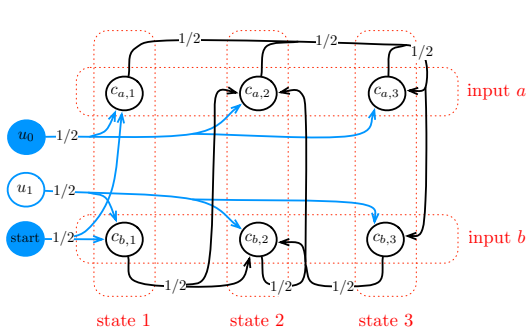
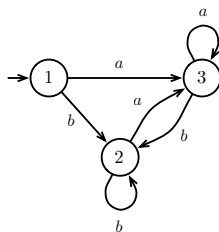
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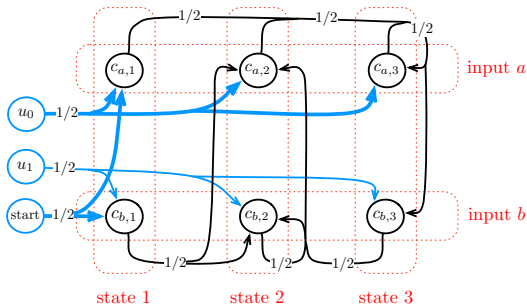
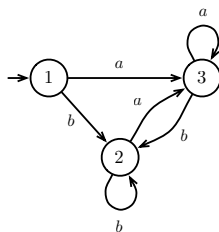
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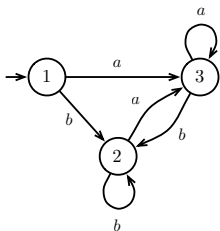




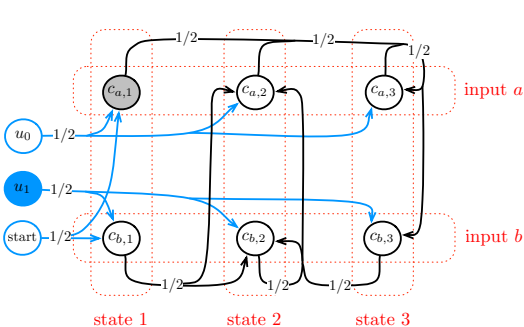


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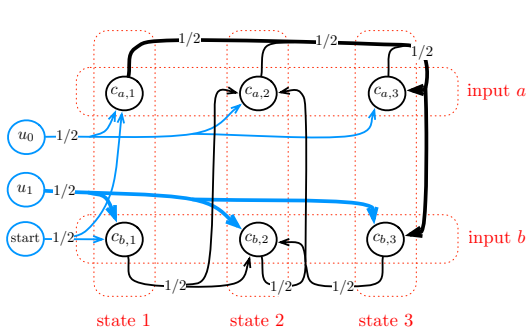
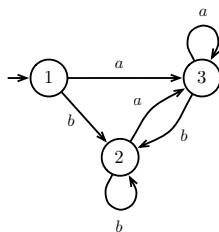
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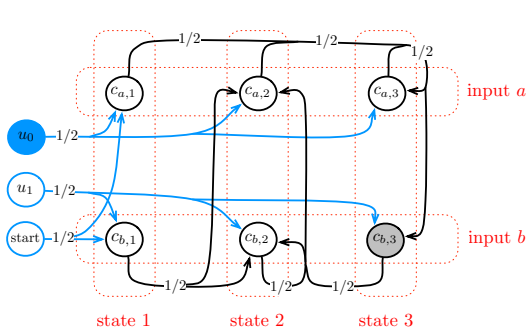
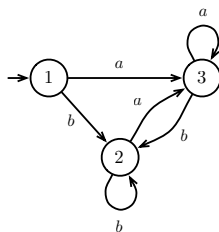


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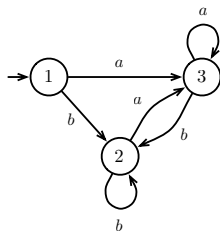
EMULATION OF FINITE STATE AUTOMATA WITH RNNs



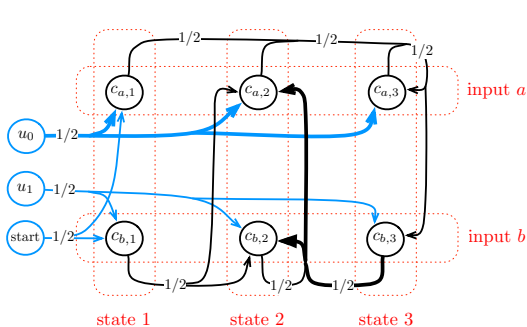


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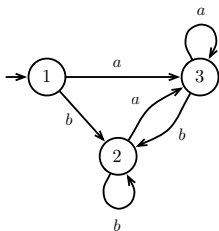


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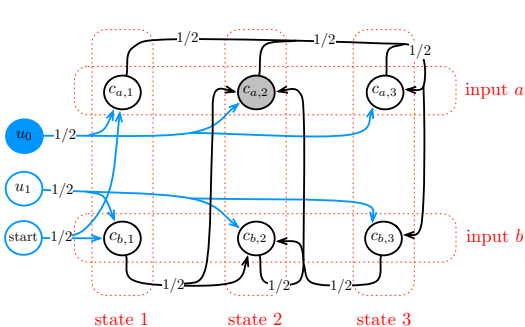


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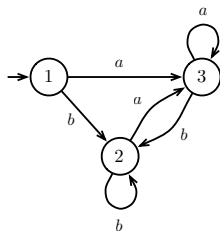


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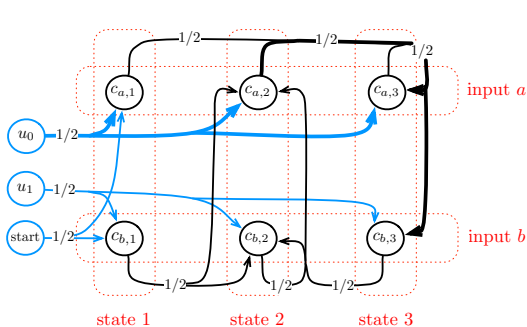


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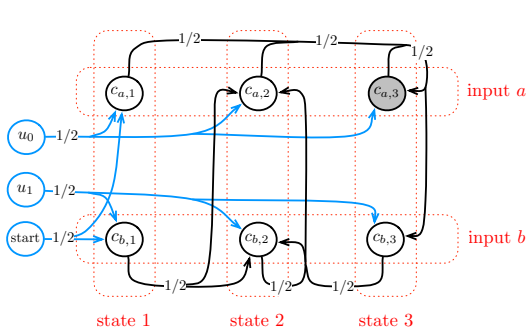
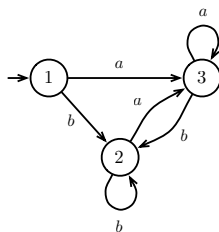
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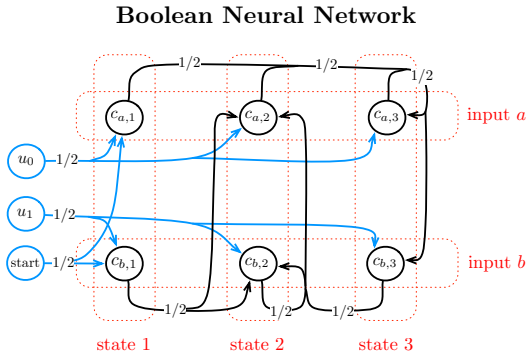
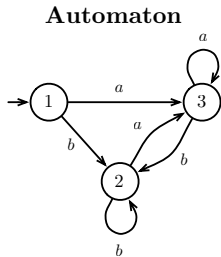


Boolean Neural Network



EMULATION OF FINITE STATE AUTOMATA WITH RNNs





$$1 \xrightarrow{a} 3 \xrightarrow{b} 2 \xrightarrow{a} 3 \xrightarrow{a} \dots \quad - \xrightarrow{(1,0)} c_{a,1} \xrightarrow{(0,1)} c_{b,3} \xrightarrow{(1,0)} c_{a,2} \xrightarrow{(1,0)} c_{a,3} \dots$$

EQUIVALENCE BETWEEN AUTOMATA AND BOOLEAN NEURAL NETWORKS

THEOREM (MINSKY 67)

"It is evident that each neural network of the kind we have been considering is a finite-state machine."

"[...] It is interesting and even surprising that there is a converse to this. Every finite-state machine is equivalent to, and can be "simulated" by, some neural net."

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DRAWBACKS OF THE CONSTRUCTION

Two main drawbacks of this construction:

- ▶ Computational states of the automaton represented by single spiking configurations (or activation vectors) of the network.
- ★ Computational states should rather be represented by *sustained activity of neural assemblies*.
- ▶ Network not robust to changing of weights or removal of connections.
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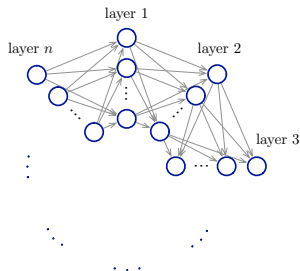
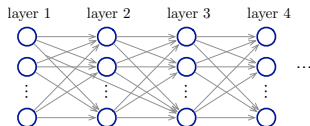
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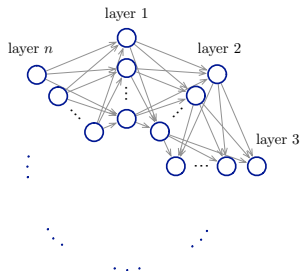
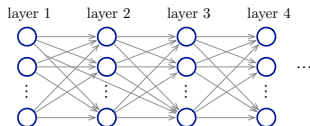
SYNFIRE CHAINS AND SYNFIRED RINGS

- *Synfire chains* are likely to be crucially involved in the processing and coding of information (ABELES 82).
- Spontaneous emergence of *synfire rings* (looping synfire chains) has been observed in self-organizing neural networks (ZHENG & TRIESCH 14).
- ★ *Computational states could be represented as sustained activities within synfire rings.*



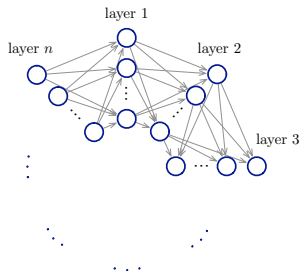
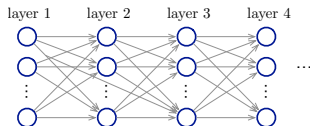
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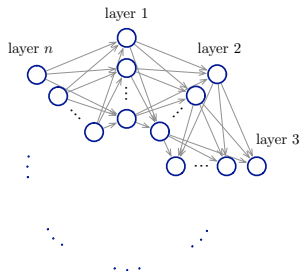
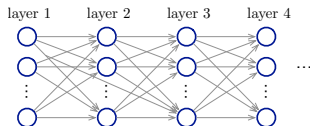
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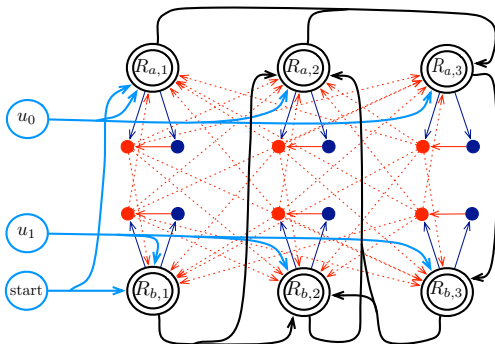
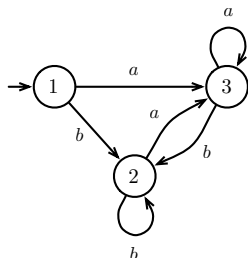


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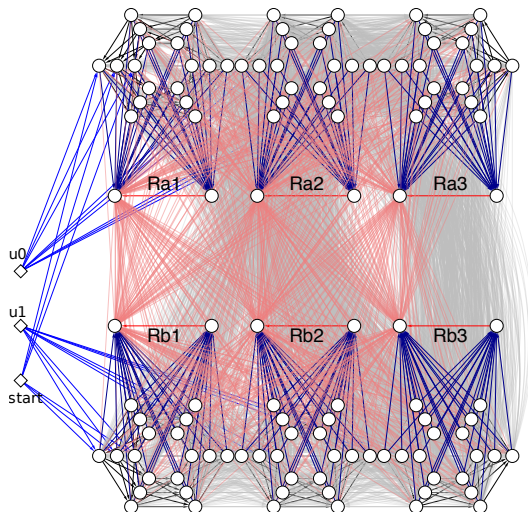
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FROM AUTOMATA TO BOOLEAN NEURAL NETWORKS WITH SYNfire RINGS



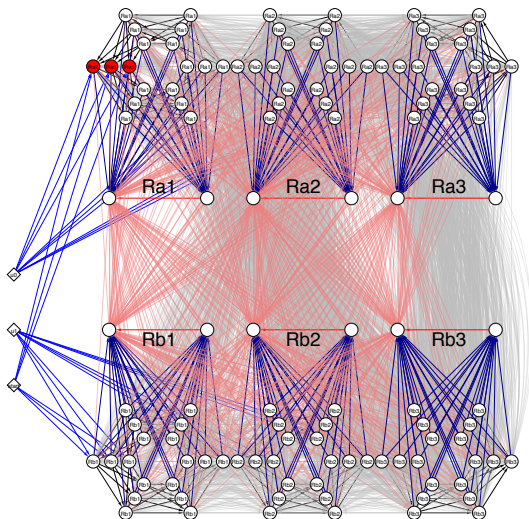
SIMULATION



EMULATION OF FINITE STATE AUTOMATA WITH RNNs



SIMULATION



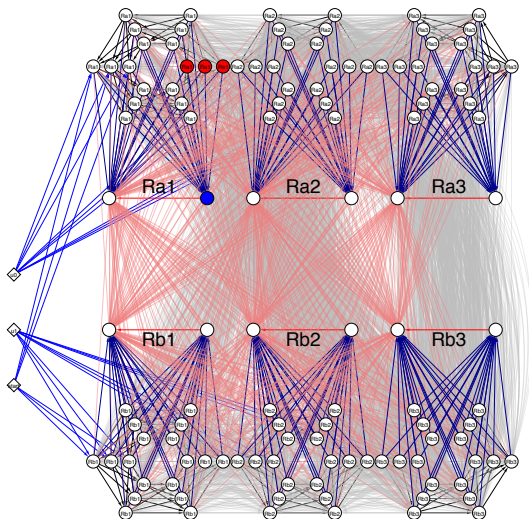
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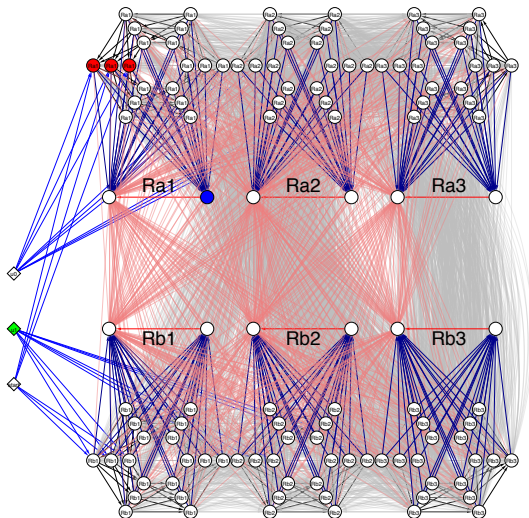
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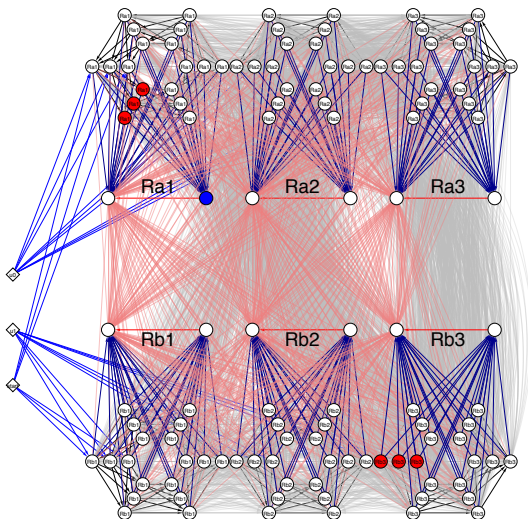
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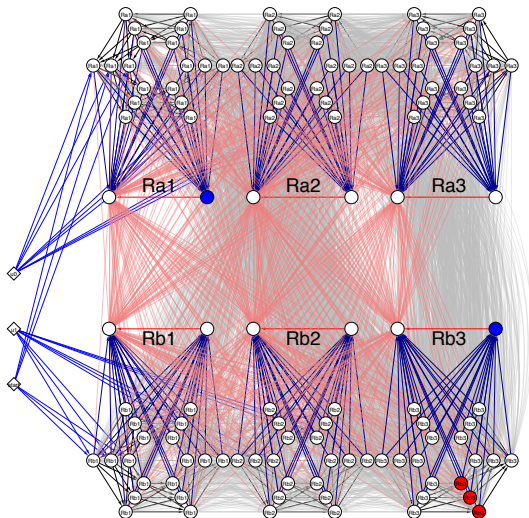
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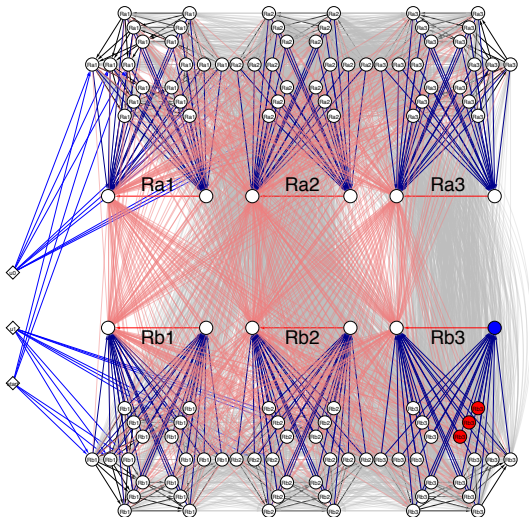
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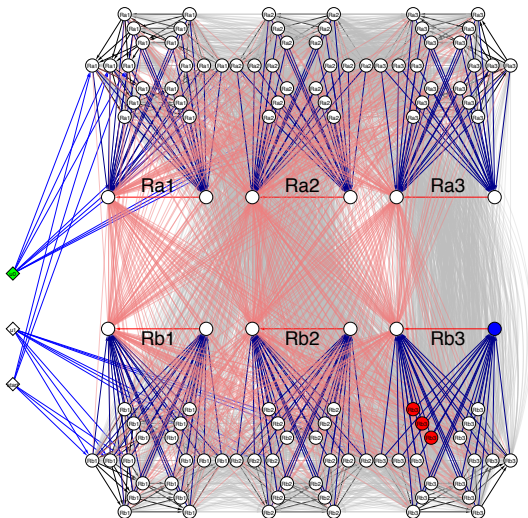
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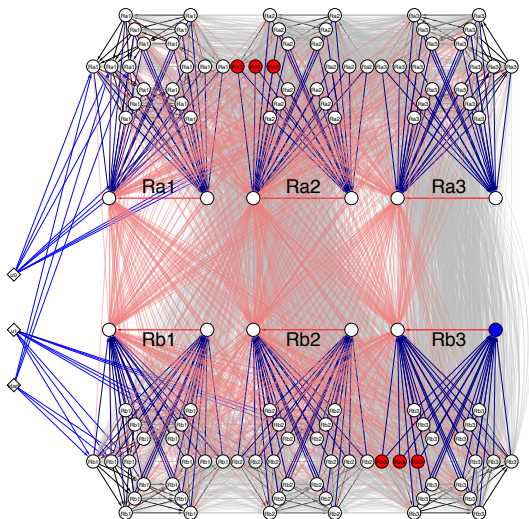
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SIMULATION



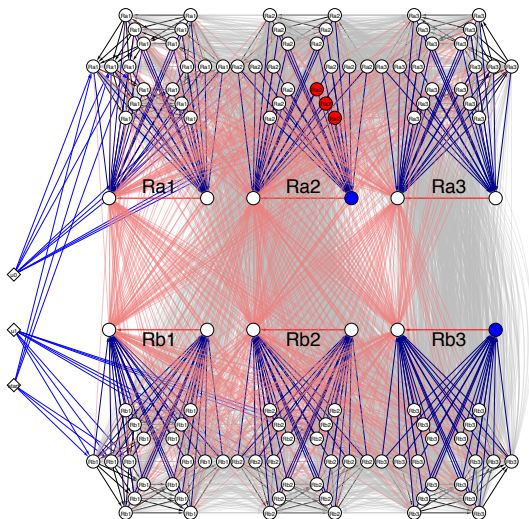
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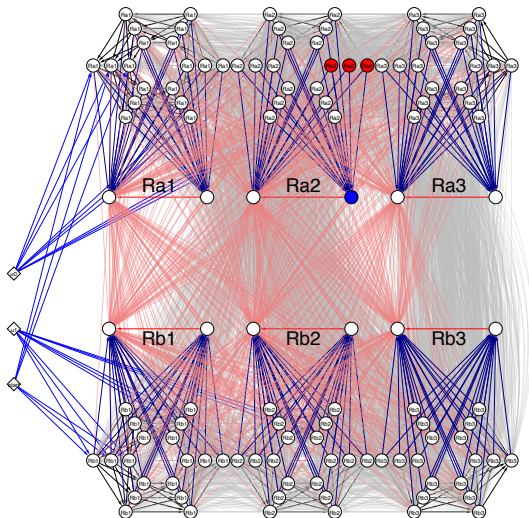
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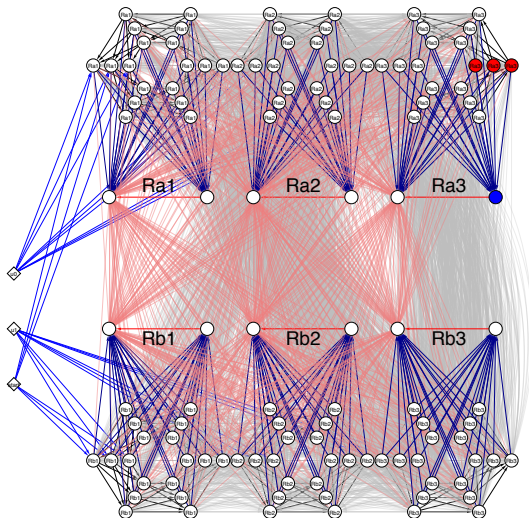
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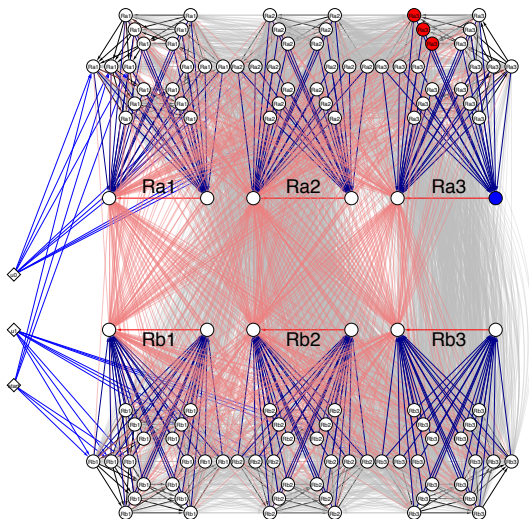
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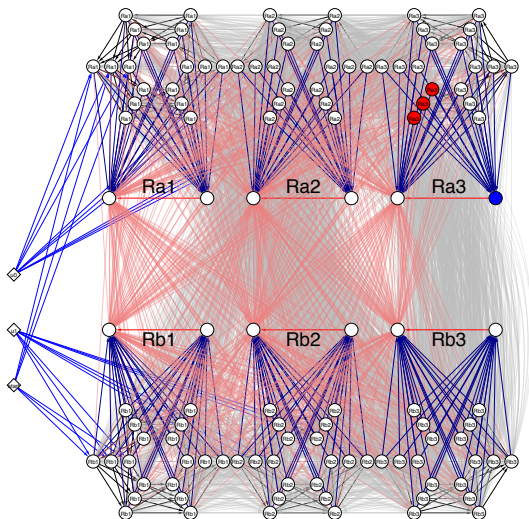
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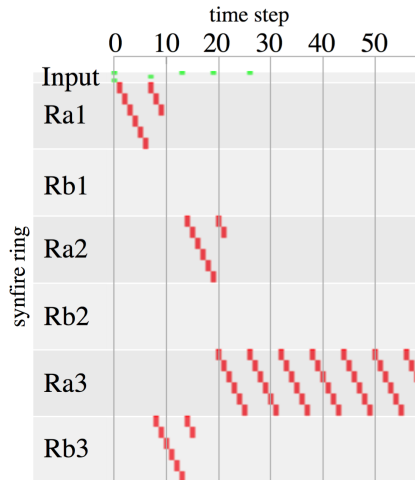
SIMULATION



EMULATION OF FINITE STATE AUTOMATA WITH RNNs



SIMULATION



ROBUSTNESS

TABLE: Robustness when inter-ring connections are removed.

Connection removal coeff.	Avg number of steps	Performance
0.50	12.00	100.0%
0.55	12.00	100.0%
0.60	12.00	100.0%
0.65	11.45	95.4%
0.70	11.20	93.3%
0.75	10.30	85.8%
0.80	7.58	63.1%
0.85	6.85	57.1%
0.90	4.17	34.8%
0.95	3.75	31.2%

ROBUSTNESS

TABLE: Robustness when intra-ring connections are removed.

Connection removal coeff.	Avg number of steps	Performance
0.00	12.00	100.0%
0.05	12.00	100.0%
0.10	12.00	100.0%
0.15	12.00	100.0%
0.20	12.00	100.0%
0.25	11.78	98.1%
0.30	11.72	97.7%
0.35	10.35	86.2%
0.40	10.05	83.8%
0.45	7.58	63.1%
0.50	6.70	55.8%
0.55	4.62	38.5%
0.60	3.05	25.4%
0.65	2.15	17.9%
0.70	1.57	13.1%
0.75	1.40	11.7%
0.80	1.12	9.4%
0.85	1.10	9.2%
0.90	1.02	8.5%
0.95	1.00	8.3%

AUTOMATA & BOOLEAN RNNs WITH SYNfire RINGS

Since the construction is generic, one has the following result:

THEOREM

Any finite state automaton can be simulated by some Boolean neural network composed of synfire rings.

IZHIKEVICH SPIKING NEURAL NETWORKS

We extend the construction to the case of Izhikevich Spiking RNNs, i.e., where each neuron's dynamics is governed by:

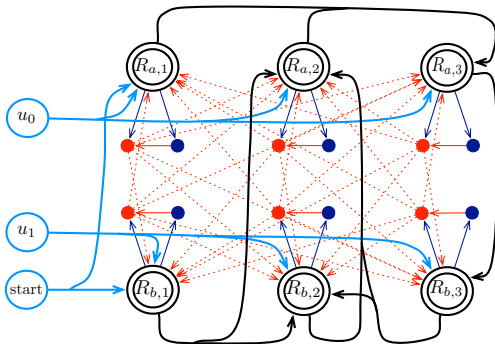
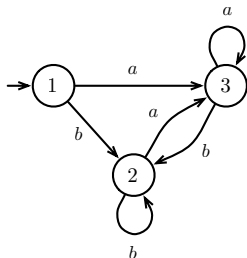
$$\begin{cases} v' &= 0.04v^2 + 5v + 140 - u + I \\ u' &= a(bv - u) \end{cases}$$

with the auxiliary after-spike resetting:

$$\text{if } v \geq 30 \text{ mV, then } v \leftarrow c \text{ and } u \leftarrow u + d$$

- ▶ v : membrane potential
- ▶ u : membrane recovery variable
- ▶ I : synaptic currents
- ▶ a, b, c, d : dimensionless parameters

FROM AUTOMATA TO SPIKING NEURAL NETWORKS WITH SYNfire RINGS



SIMULATION: WITHOUT SYNAPTIC NOISE

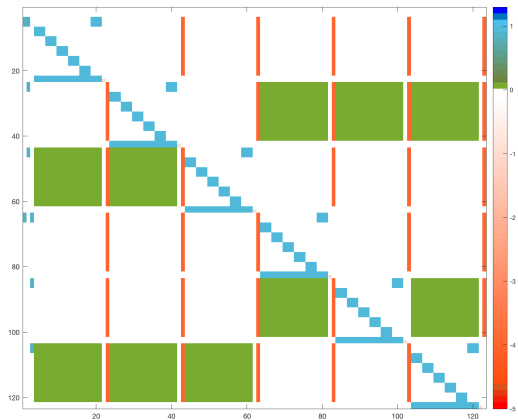


FIGURE: Connectivity matrix of the network



SIMULATION: WITHOUT SYNAPTIC NOISE

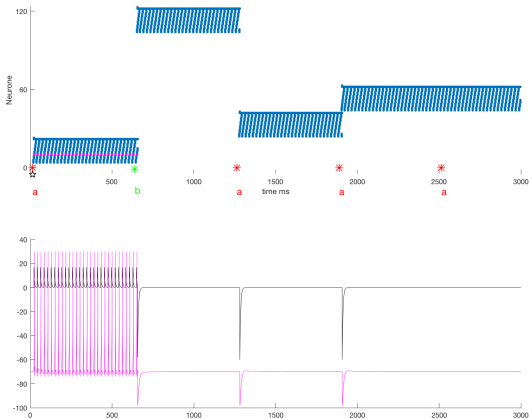


FIGURE: Raster plot of the simulation and activity of one spiking neuron



SIMULATION: WITHOUT SYNAPTIC NOISE

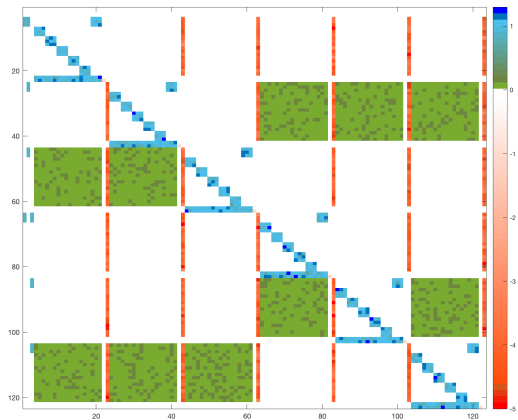


FIGURE: Connectivity matrix of the network

AUTOMATA & SPIKING RNNs WITH SYNfire RINGS

Since the construction is generic, one has the following result:

THEOREM

Any finite state automaton can be simulated by some (noisy) Izhikevich spiking neural network composed of synfire rings.

CONCLUSIONS

- ▶ We showed that any finite state automaton can be simulated by some spiking RNN composed of synfire rings.
- ▶ The computational states are represented as sustained activities of neural assemblies rather than by static states (or activation vectors) of the network.
- ▶ We intend to show that abstract models of computation – rather than single specific problems – can be implemented in bio-inspired neural networks.
- ▶ Future work along these lines: towards Turing complete computation.

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